

Near infrared hyperspectral imaging – background and application for wood characterization

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**2nd Workshop on application of NIR spectroscopy
for wood science and technology research**

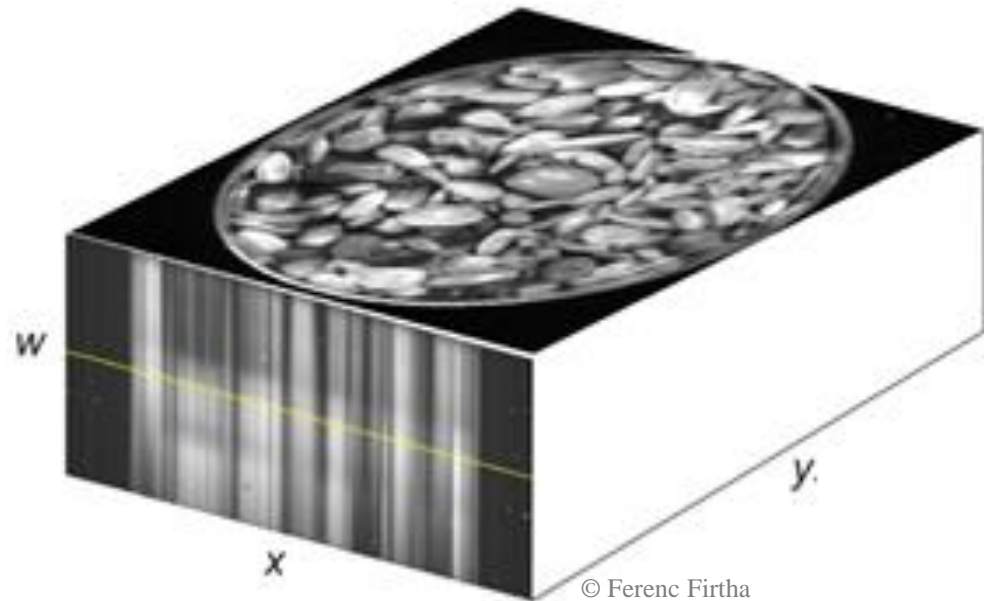
NIR & WOOD – SOUNDS GOOD! #2

April 19-21, 2016

CNR-IVALSA, Via Biasi 75, 38010 San Michele all' Adige, Italy

Content

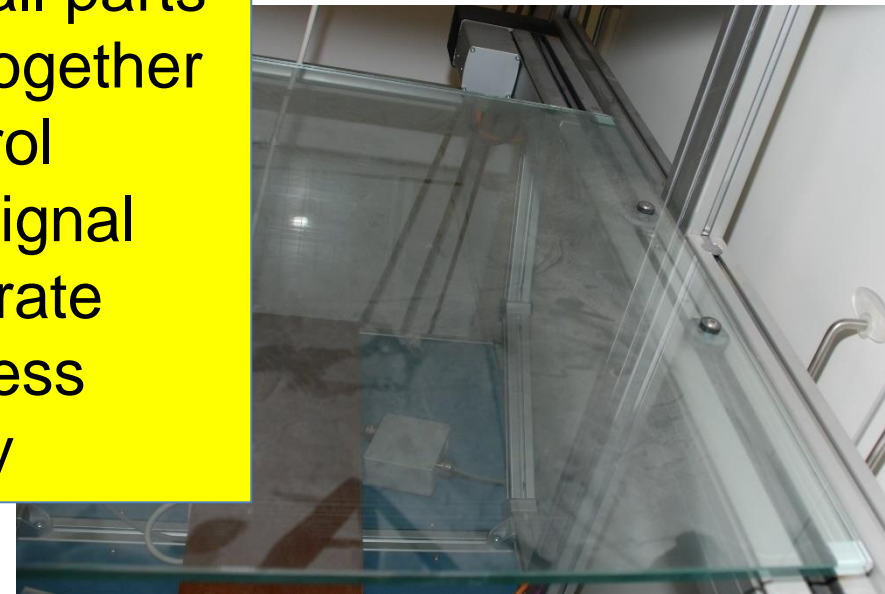
- My personal contact history with HSI
- General background
- Technical information
- First results
- General workflow
- Analytical challenges



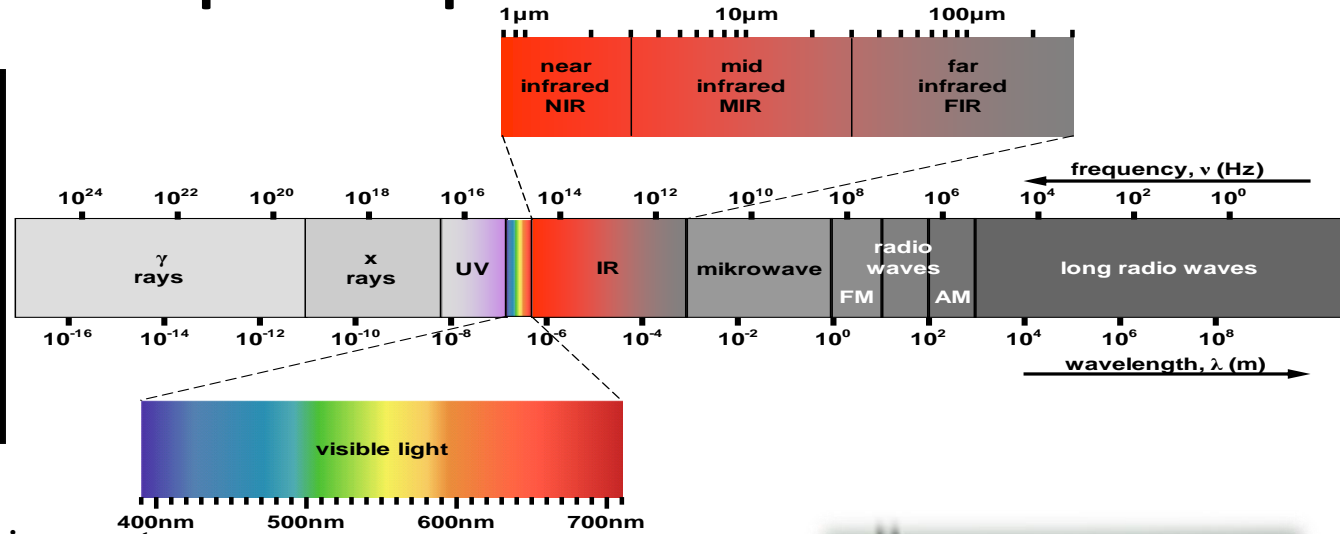
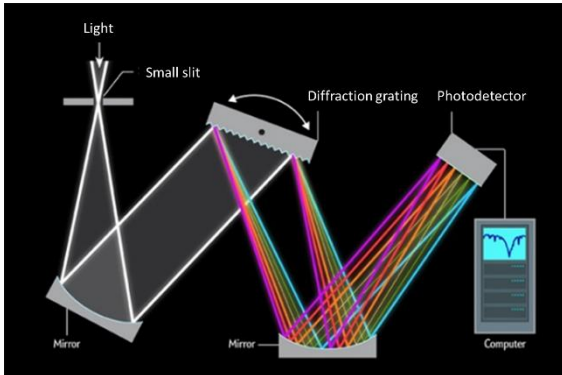
My first contact...

I had to

- understand
- find all parts
- put together
- control
- get signal
- calibrate
- process
- apply



Spectral sensing – principles

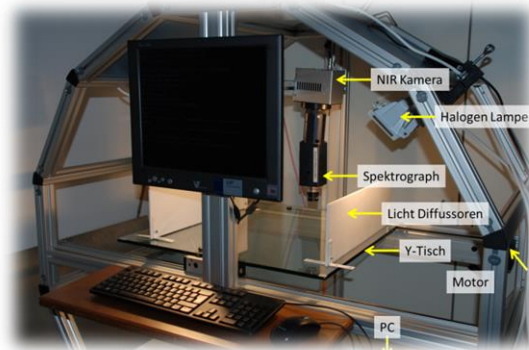
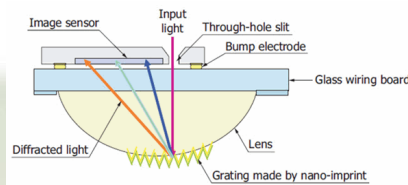
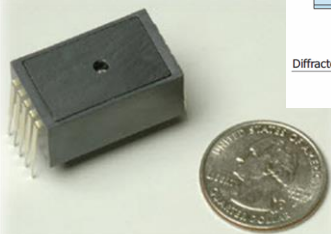


- Part of the electromagnetic spectrum
- Visible light~ 390-700 nm
- Near infrared~ 780 nm and 3 μm

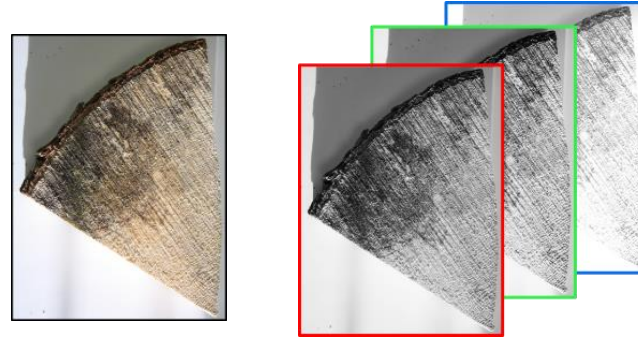
„Classical“ FT-NIR with fibre probe

„Hyperspectral“ Imaging

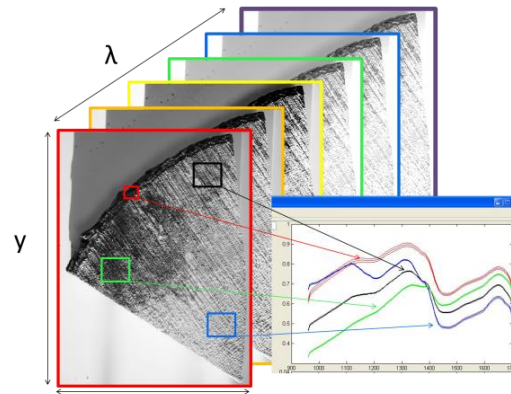
Mini Sensors



Difference RGB, multi- und hyperspectral

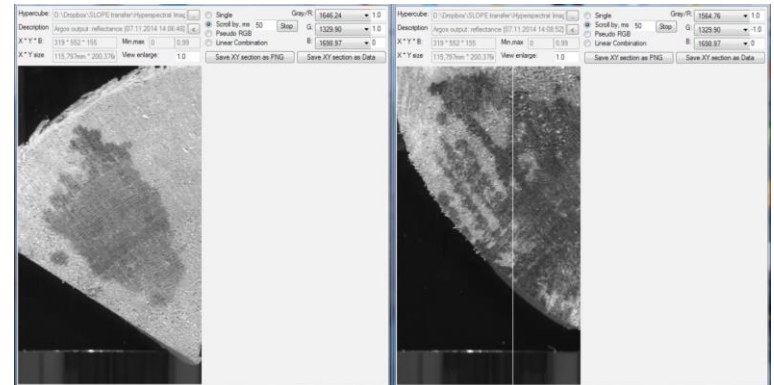
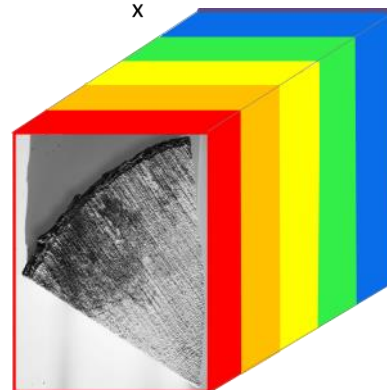
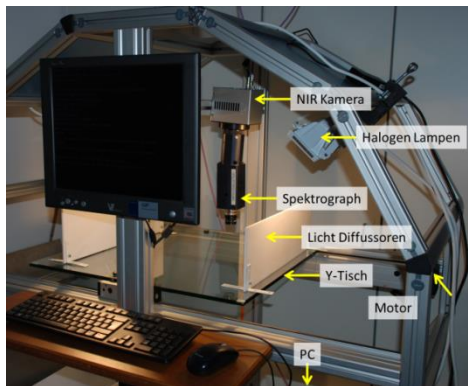


RGB: 3 wavelengths

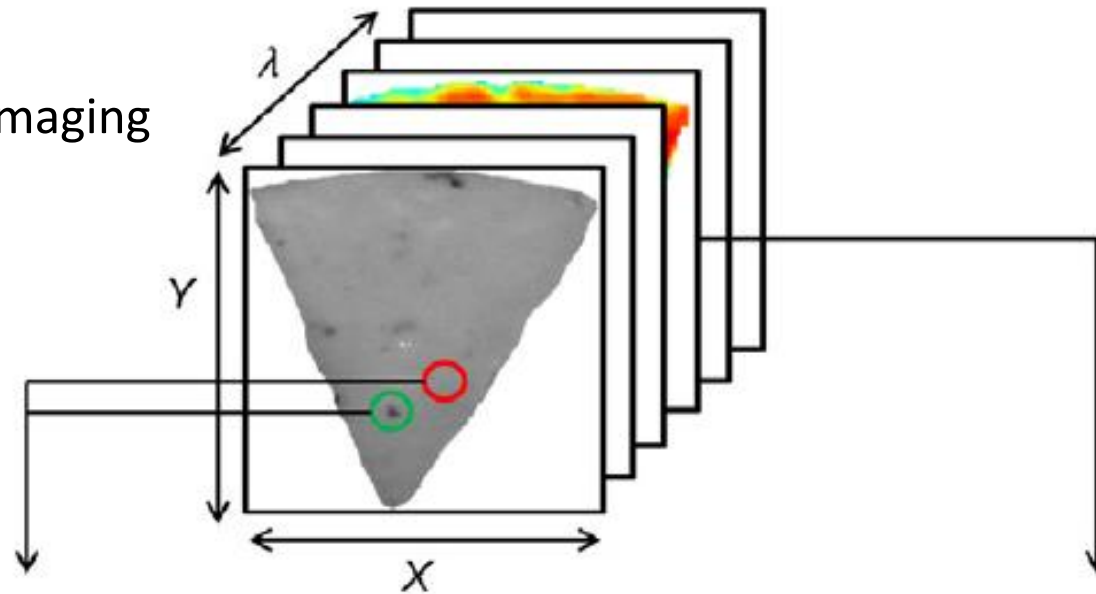


Multi: 4-10 wavelengths

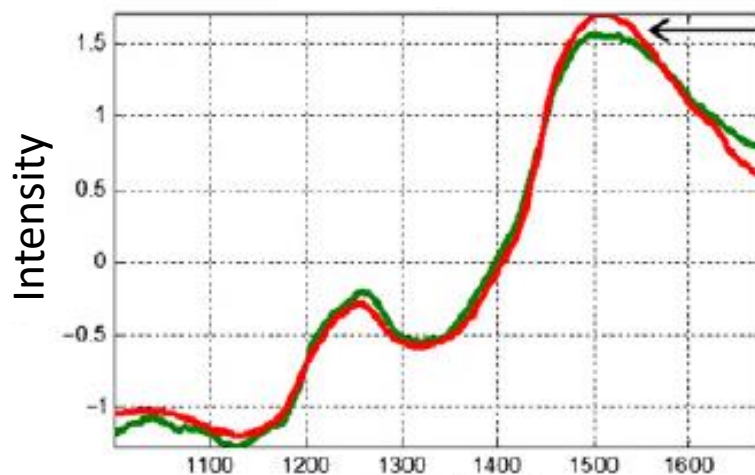
Hyper: 100 wavelengths
quasi continuous (in nm steps)



Combination of
spectroscopy with Imaging

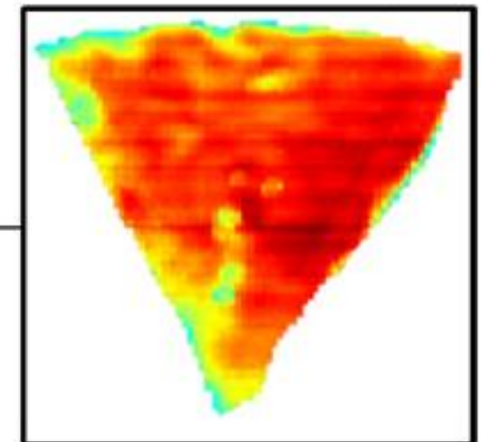


Pixel spectra

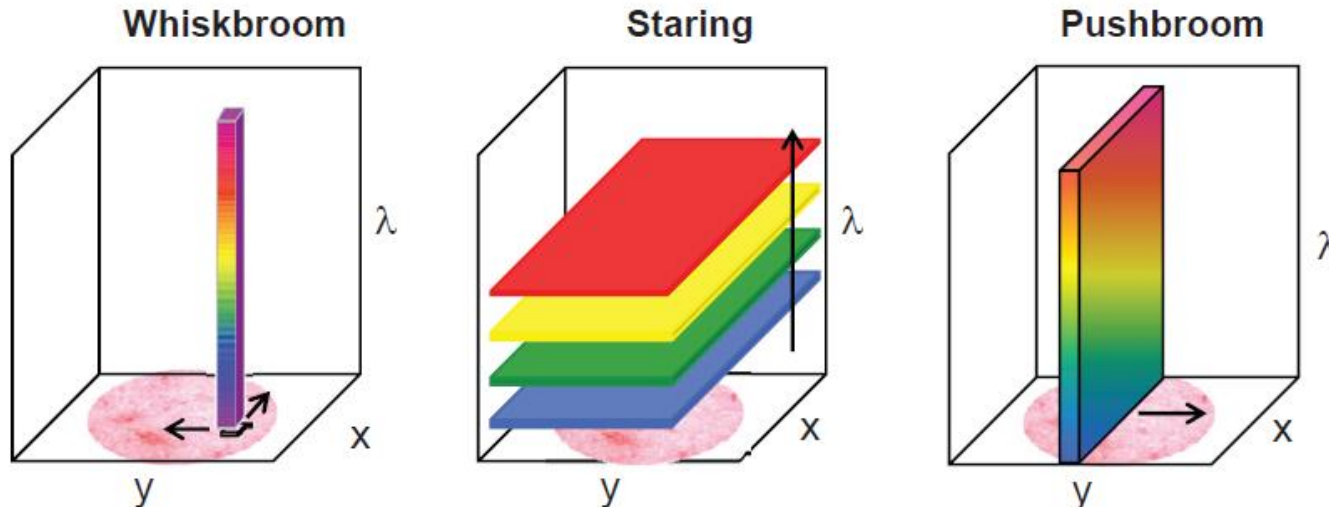


Wavelength (nm)

Image at wavelength λ



HSI – general setups

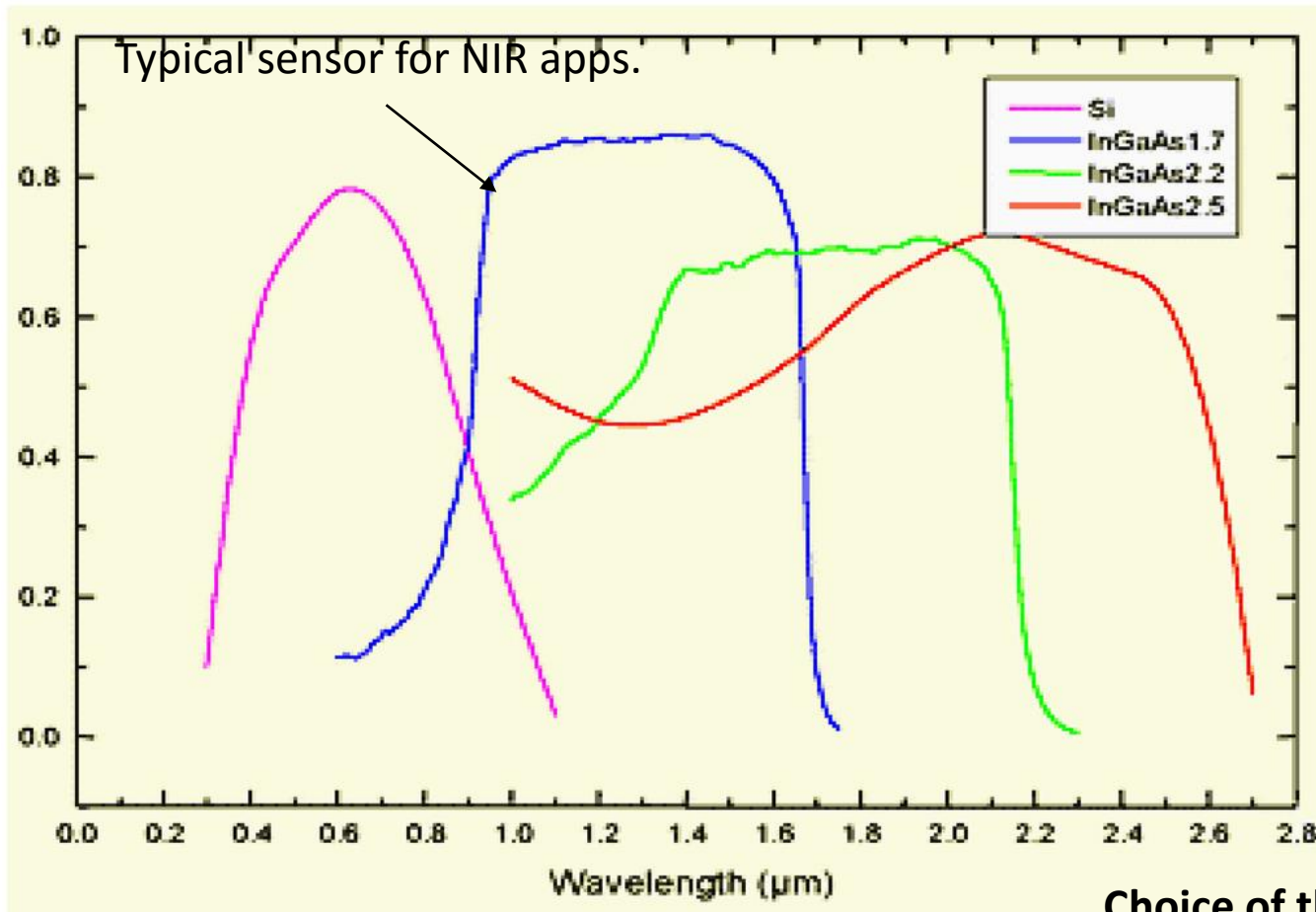


From: BOLDRINI, B., KESSLER, W., REBNER, K. & KESSLER, R. W., 2012. Hyperspectral imaging: a review of best practice, performance and pitfalls for inline and online applications. *Journal of Near Infrared Spectroscopy*, 20 (5): 438-508.

- **Whiskbroom imaging :** During whiskbroom imaging the sample is scanned pixel per pixel in the x-y-spatial direction in a sequential manner.
- **Staring (staredown) imaging:** Staring imaging is done by a two-dimensional camera capturing the spectral information in each pixel x-, y-plane at once.
- **Pushbroom imaging:** Pushbroom imaging as a line scanning system acquires the information for each pixel in the line at once.

Sensor types

– and their sensitivities in different wavelength ranges



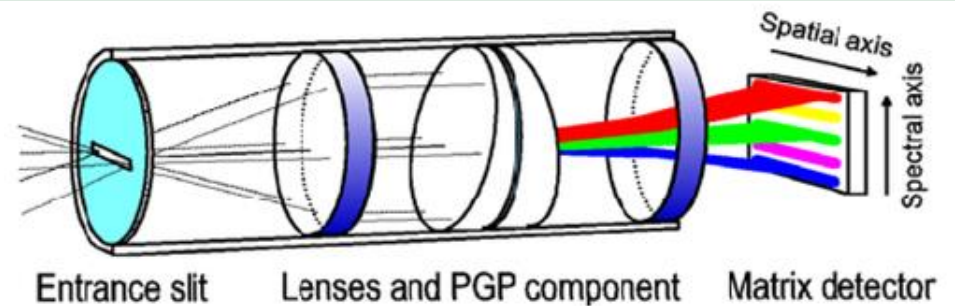
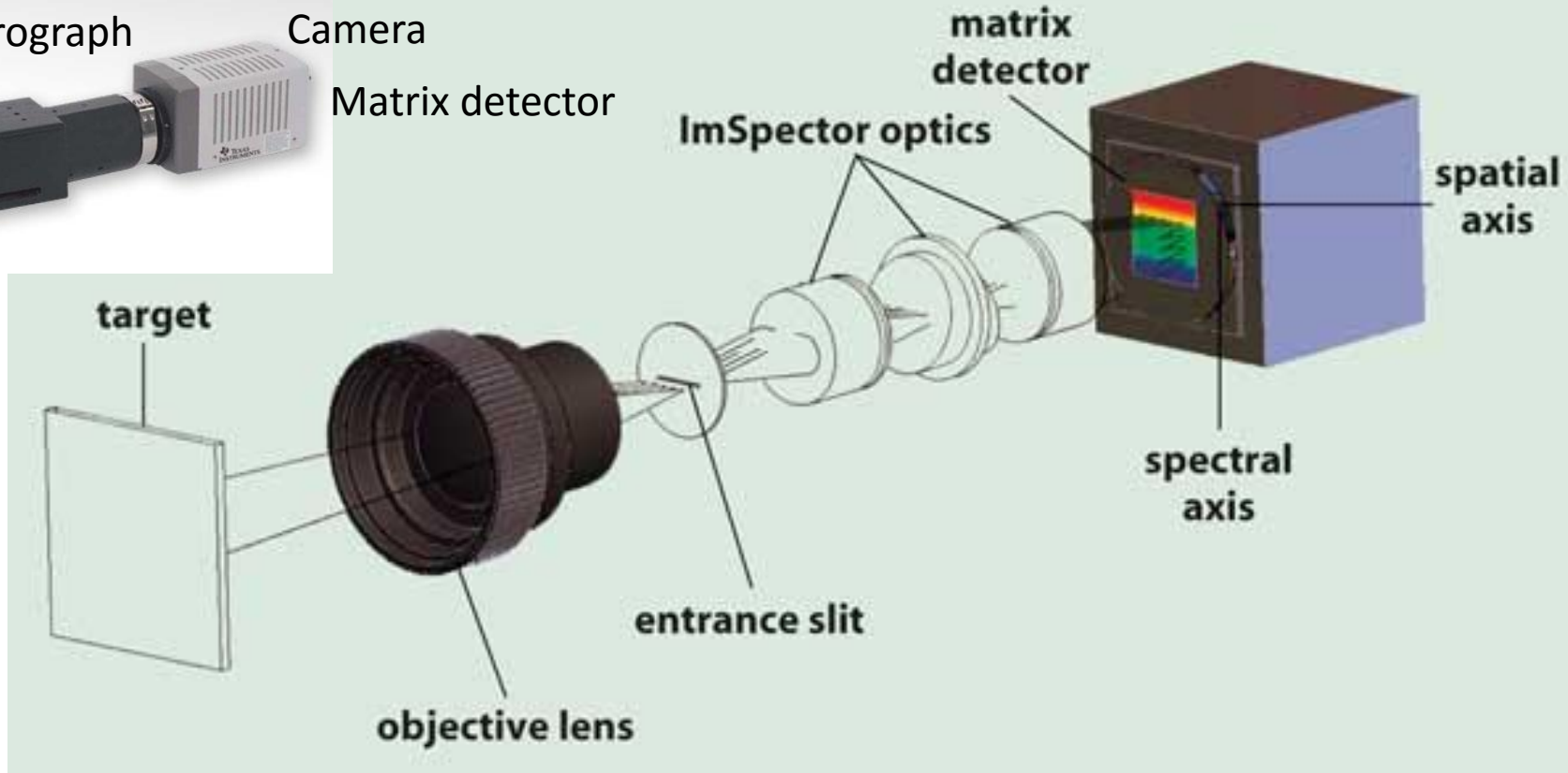
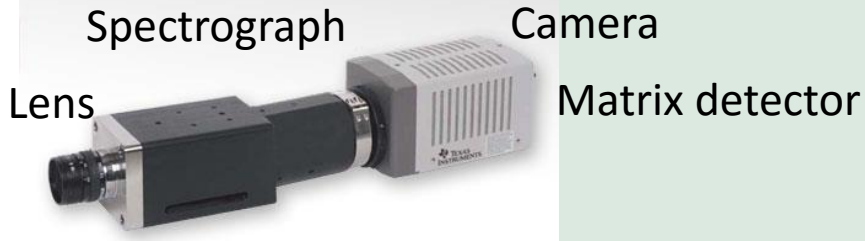
Sensor types

- silicon (Si)-based charge-coupled device (CCD)
- complementary metal oxide semiconductor (CMOS) cameras,
- **indium gallium arsenide (InGaAs)-based array detectors,**
- mercury cadmium telluride (HgCdTe)-based array detectors.

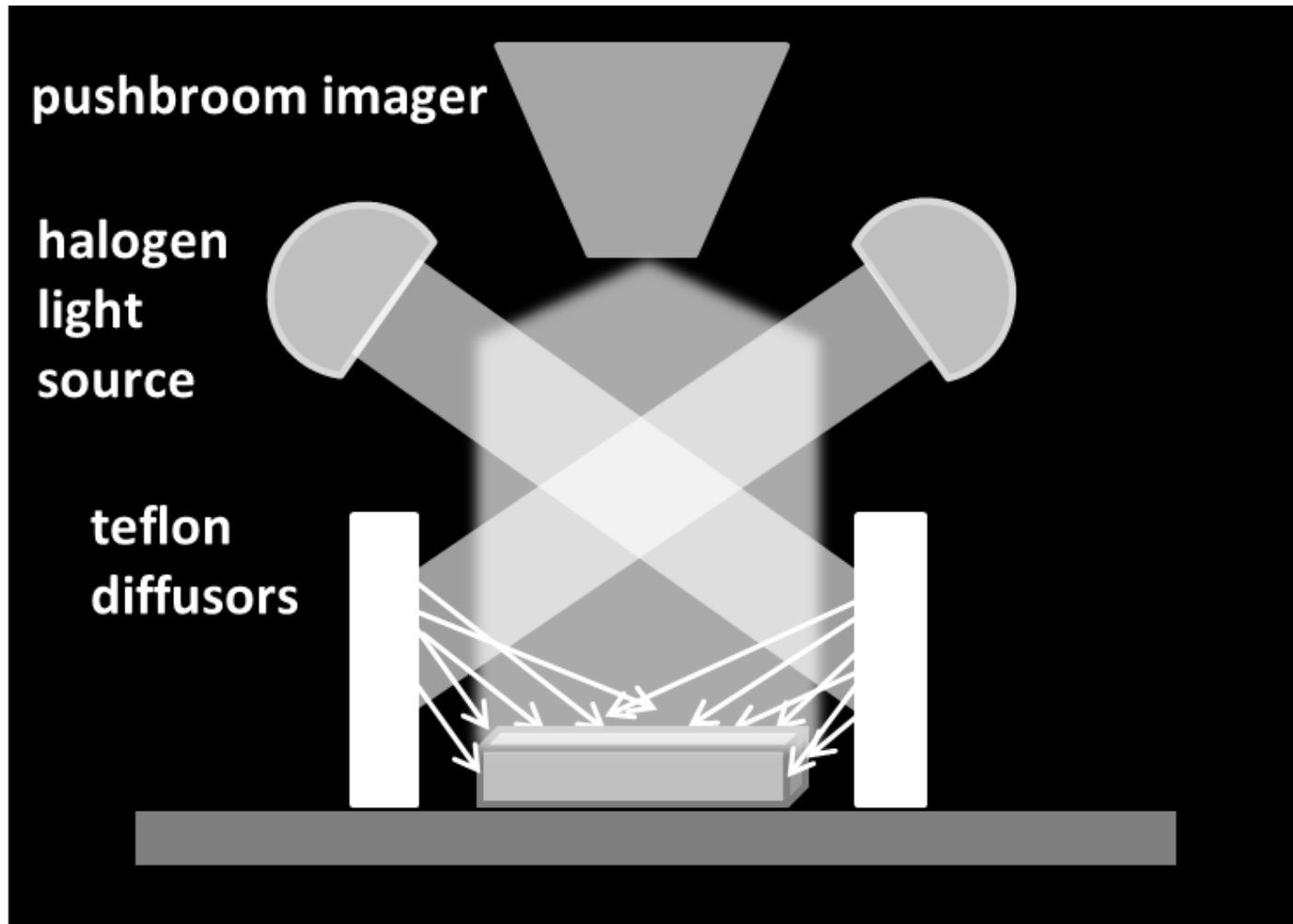
Choice of the sensor depends on:

- the required wavelength,
- the quantum efficiency = sensitivity,
- and the cost.

spectrograph and camera



(„spectral input“) for NIR imaging



(after Boldrini *et al.* 2012).

for imaging and analysis

ARGUS data acquisition software

F. Firtha, Argus hyperspectral acquisition software,
ftp://fizika2.kee.hu/ffirtha/Argus-CuBrowser.pdf,
(2010)

Cubrowser data browsing and pre-processing software

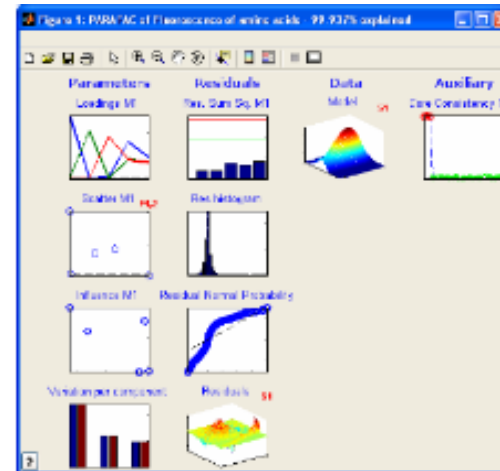
F. Firtha, CuBrowser hyperspectral data processing
algorithm ftp://fizika2.kee.hu/ffirtha/Argus-
CuBrowser.pdf, (2012).

Eigenvector: PLS_toolbox, MIA, Model_exporter

Evince Software (Prediktera)

BRUKER: OPUS

CAMO: Unscrambler



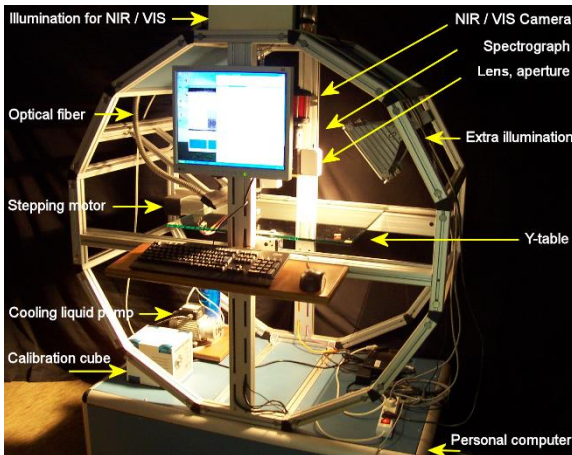
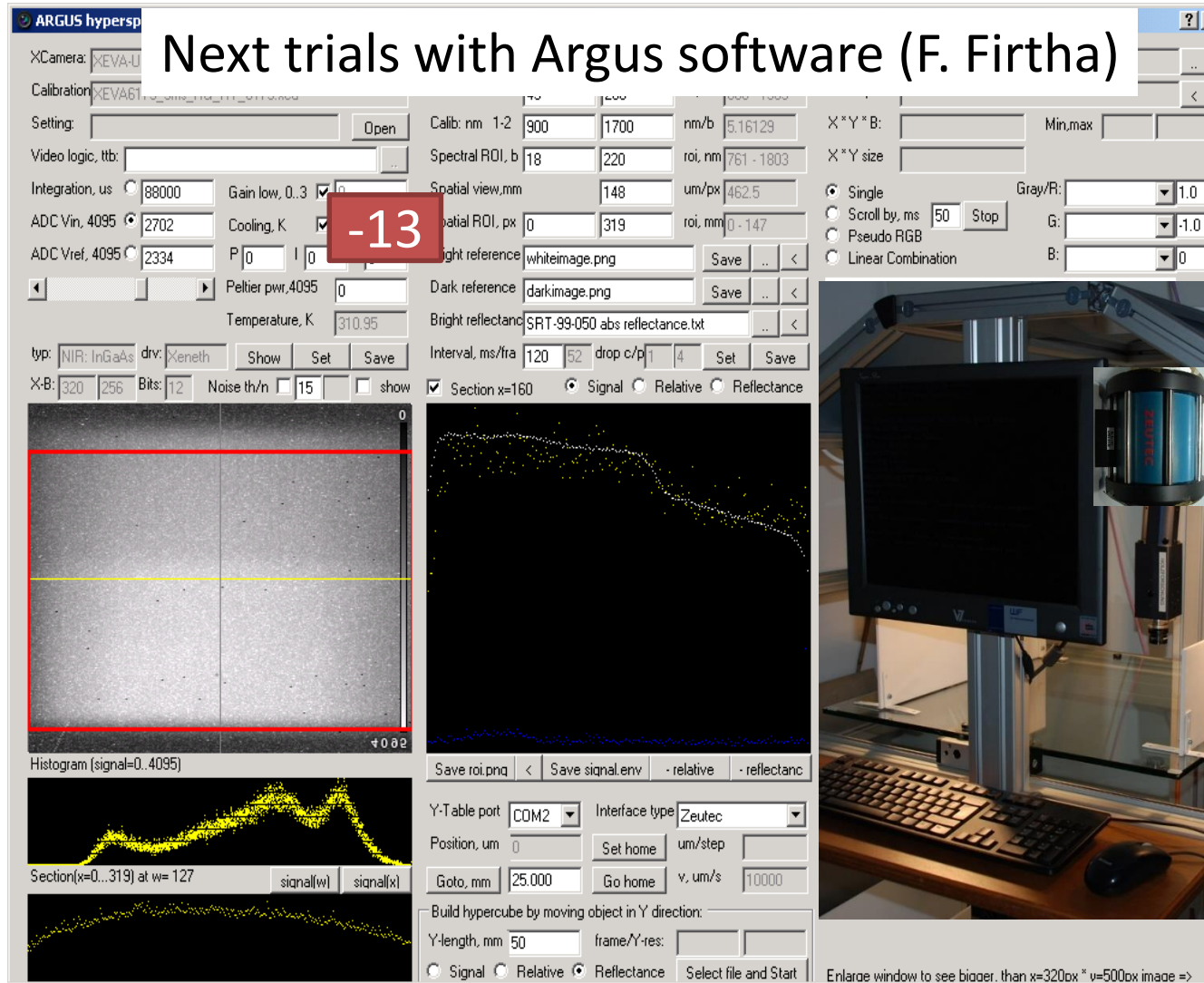


„trials with old system“

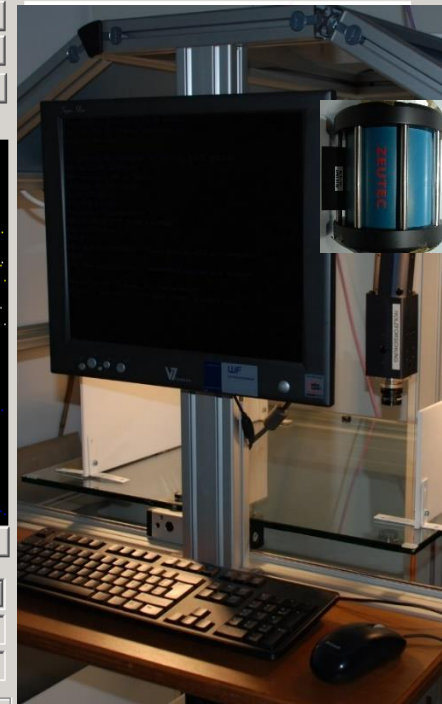
Original „ZEUTEC“ Cubico Software – not working

„Sister system“
in Hungary,
Corvinus University

Next trials with Argus software (F. Firtha)

The screenshot shows the ARGUS hypersp software interface with various control panels and data visualizations. A red box with the number -13 is overlaid on the interface. The interface includes sections for camera settings, integration parameters, calibration data, and data processing options. It also displays a histogram and a spectral plot.



Enlarge window to see bigger. than x=320px * v=500px image =>

Firtha, F., Fekete, A., Kaszab, T., Gillay, B., Nogula-Nagy, M., Kovács, Z. & Kantor, D.B. (2008) Methods for improving image quality and reducing data load of NIR hyperspectral images. *Sensors*, **8**, 3287-3298.

Exchange of camera and transfer of sensor

Xenics NIR camera Xeva-USB-FPA-1.7-320-TE1-100Hz camera with an InGaAs focal plane array sensor with 2% pixel noise – XEVA 6179; 0.9 μm to 1.7 μm ; 320*256 pixel matrix; 12 bit. Cooling of the XEVA camera down to -4 to -13 ° C (269-260° K), which is needed to reduce the noise in the images, is achieved by forced convection (TE-1) cooling.



Software update (Ferenc Firtha)

ARGUS hyperspectral data acquisition software (Firth@rt, 2015)

XCamera: XEVA-USB-FPA-320-100Hz (BUSY,IP=,PID=8110,SER=...)
 drv: Xeneth typ: NIR X-B-bit: 320 256 12
 Calibration: XEVA6179_80ms_LG_RT_new_6179.xca
 Setting: [] Open

Video logic, ttb: [] ...

Integration, us: 80000 LowGain level 0-3
 ADC Vin, 4095: 2730 Cooling settle, C: 164,8E
 ADC Vref, 4095: 2123 P: 3000 I: 150 D: 1
 Peltier: 0 temp, C: -11,32

Noise th%/n: 50 1 show AllProp Set Save
 Intvl/Dur, ms: 200 34 fra 0 / jump, tck drop: 24 66 94

Software setting: Zeutec_NIR.ini
 Calib: band1-2: 45 200 all, nm: 668 - 1989
 Calib: nm 1-2: 900 1700 nm/b: 5,16129
 Spectral ROI, b: 18 220 roi, nm: 761 - 1803
 Spatial view, mm: 135 um/px: 421,875
 Spatial ROI, px: 0 319 roi, mm: 0 - 134
 Bright frame: whiteimage.png Save ... <
 Dark frame: darkimage.png Save ... <
 AbsRef of bright: SRT-99-050 abs reflectance.txt ... <
 Section x=160 Signal Reflectance Absolute

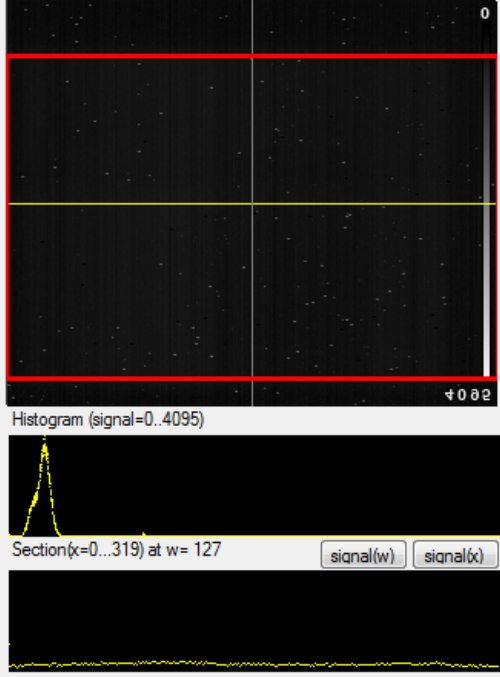
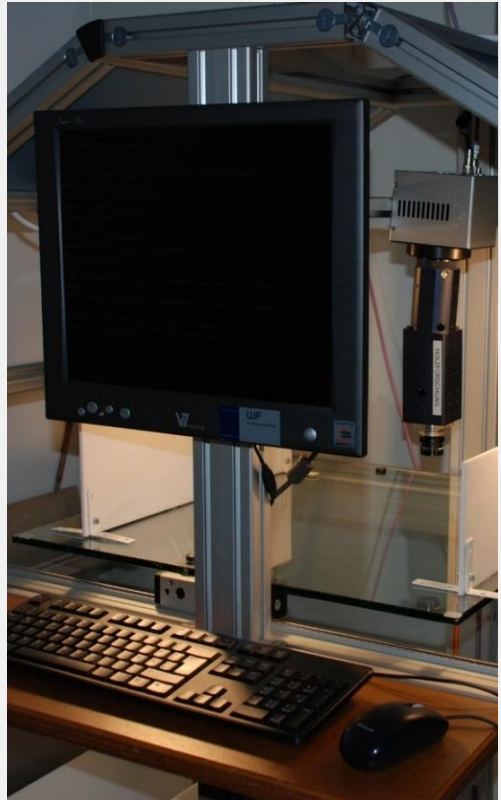
Hypercube: 0305_12_fourth Argus version_200 invl_2_log2f ...
 Description: Argos output: relative [03.05.2015 11:55:02] <
 X*Y*B: 319 * 190 * 202 Min,max: 0 1
 X*Y size: 134,618mm * 80,180
 Single Gray/R: 760.65 ▾ 1.0
 Scroll by, ms: 50 Stop G: 1276.77 ▾ -1.0
 Pseudo RGB B: 1798.06 ▾ 0
 Linear Combination

Save roi.png < Save signal.env -relative -reflectanc

Y-Table port: COM1 Interface type: Zeutec reset
 Position, um: 79250 Set home um/step
 Goto, mm: 25.000 Go home v, um/s: 10000

Build hypercube by moving object in Y direction:
 Y-length, mm: 80 frame/Y-res: 190 190
 Signal Reflectance Absolute Select file and Start

Enlarge window to see bigger, than x=320px * y=500px image =>

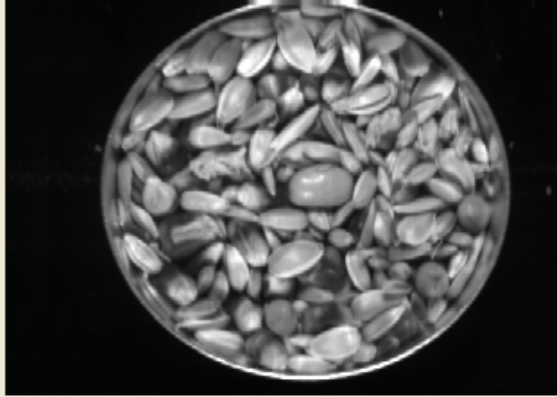
ARGUS hyperspectral data acquisition software (v2012.11.30, Firth@rt software - Corvinus University of Budapest, SharpDevelop 4.4.1 - dotNet 4.5.1)

XCamera: XEVA-CL-FPA-320-100Hz (PID=8637,SER=1648)
 Calibration: XEVA1648_TrueNUC_HG_RT_1648.xca
 Setting: [] [Open]
 Video logic, ttb: [] [..]
 Integration, us: 82000 Gain low, 0..3: 1
 ADC Vin, 4095: 3824 Cooling, K: 273
 ADC Vref, 4095: 2474 P: 0 I: 0 D: 0
 Peltier pwr, 4095: 0 Temperature, K: 292.30
 typ: NIR: InGaAs drv: Xeneth [Show] [Set] [Save]
 X-B: 320 256 Bits: 14 Noise th/n: 15 show

Software setting: XevaNIR_hiper.ini
 Calib: band1-2: 59 175 all, nm: 698 - 1924
 Calib: nm 1-2: 980 1536 nm/b: 4,793103
 Spectral ROI, b: 55 210 roi, nm: 961 - 1703
 Spatial view, mm: 116 um/px: 362,5
 Spatial ROI, px: 0 319 roi, mm: 0 - 115
 Bright reference: whiteimage.png [Save] [..] [
 Dark reference: darkimage.png [Save] [..] [
 Bright reflectanc: SRT-99-050 abs reflectance.txt [..] [
 Interval, ms/fra: 120 33 drop c/p: 40 12 [Set] [Save]

Hypercube: parrotfood.hdr
 Description: Argos output: reflectance [2014.06.05. 17:15:17] [
 X * Y * B: 319 * 276 * 155 Min,max: 0 0,99
 X * Y size: 115,797mm * 100,18
 Single Gray/R: 1420.97 [v] 1.0
 Scroll by, ms: 50 [Stop]
 Pseudo RGB G: 1329.90 [v] -1.0
 Linear Combination B: 1698.97 [v] 0

Section x=106 Signal Relative Reflectance



Histogram [signal=0..16383]
 Section(x=0...319) at w= 133 [signal(w)] [signal(x)]

Save roi.png [
 Save signal.env [
 - relative [
 - reflectanc [
 Y-Table port: COM1 [v] Interface type: HeadWall [v]
 Position, um: 5 [Set home] um/step: [v]
 Goto, mm: 50 [Go home] v, um/s: 10000
 Build hypercube by moving object in Y direction:
 Y-length, mm: 100 frame/Y-res: 276 276
 Signal Relative Reflectance [Select file and Start]

Enlarge window to see bigger, than x=320px * y=500px image =>

Opening, AD parameters, tuning focus: ARGUS left panel

The screenshot shows the ARGUS software interface with the following sections:

- XCamera:** XEVA-CL-FPA-320-100Hz (PID=8637_SER=1648)
- Calibration:** XEVA1648_TrueNUC_HG_RT_1648.xca
- Setting:** [Empty field] [Open]
- Video logic, ttb:** [Empty field] [...]
- Integration, us:** 82000
- Gain low, 0..3:** 1
- ADC Vin, 4095:** 3824
- Cooling, K:** 273
- ADC Vref, 4095:** 2474
- P:** 0
- I:** 0
- D:** 0
- Peltier pwr, 4095:** 0
- Temperature, K:** 292.30
- typ:** NIR: InGaAs
- drv:** Xeneth
- Show** **Set** **Save**
- X-B:** 320 256
- Bits:** 14
- Noise th/n:** 15
- show**

Actual $R(x,b)$ frame as a grayscale image: A grayscale image showing vertical spectral lines. A red rectangle highlights a spectral and spatial region of interest (ROI). A yellow horizontal line indicates a spectral cross-section at a selected point.

Histogram of signal: A plot titled "Histogram (signal=0..16383)" showing a peak in the signal distribution.

Spatial cross section of frame: A plot titled "Section(x=0...319) at w= 133" showing the signal intensity across the spatial dimension. It includes buttons for "signal[w]" and "signal[x]".

open NIR sensor
and calibration file containing basic parameters

1

integration time and gain to get optimal signal level

2

sensor cooling

3

actual $R(x,b)$ frame as a grayscale image

- spectral and spatial region of interest (ROI) is shown by red rectangle
- spectral (gray) and spatial (yellow) cross sections at selected point

histogram of signal

spatial cross section of frame
to check homogeneity of illumination
to tune focus plane of lens by contrast



Calibration, data acquisition: ARGUS middle panel

2-point spectral calibration

spectral and spatial ROI
spatial calib → px size

saving bright/low surfaces
→ reflectance factor
→ absolute reflectance

spectral crosssection of frame:

reflectance spectrum (yellow)
between bright and dark signal

controlling Y-table
go to anywhere and back

set Y length
and start measurement

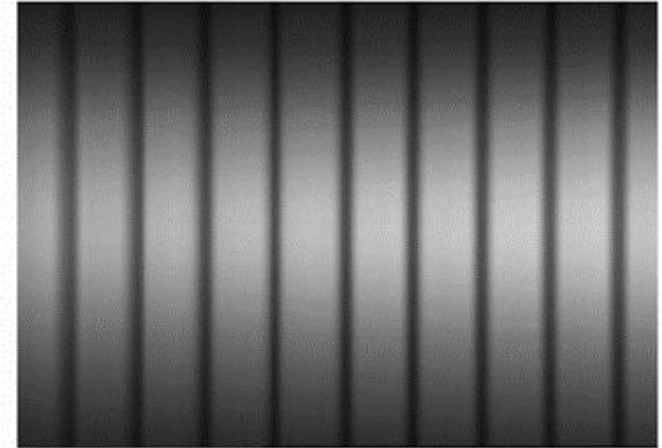
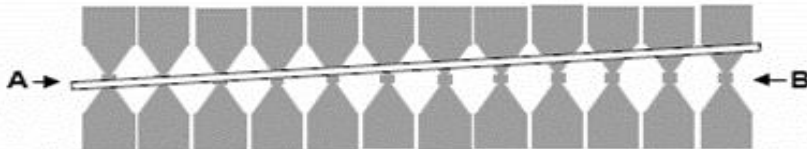
The screenshot displays the ARGUS software interface. At the top, the 'Software setting' is 'XeVaNIR_hiper.ini'. Calibration parameters include 'Calib: band1-2' (59, 175) and 'all, nm' (698 - 1924). 'Calib: nm 1-2' is set to 980 and 1536, with 'nm/b' at 4,793,103. 'Spectral ROI, b' is 55 and 210, with 'roi, nm' at 961 - 1703. 'Spatial view, mm' is 116, 'um/px' is 362,5. 'Spatial ROI, px' is 0 and 319, with 'roi, mm' at 0 - 115. Reference files are 'whiteimage.png' and 'darkimage.png'. 'Bright reflectanc' is 'SRT-99-050 abs reflectance.txt'. 'Interval, ms/fra' is 120, 33, 'drop c/p' is 40, 12. The 'Section x=106' is checked. Radio buttons are set to 'Signal'. The plot shows a yellow curve (reflectance spectrum) between a bright (dotted) and dark (dotted) signal. The Y-axis is labeled '50' in a yellow box. The 'Y-Table port' is 'COM1', 'Interface type' is 'HeadWall', 'Position, um' is 5, 'Goto, mm' is 50, 'Go home' is set, 'v, um/s' is 10000. 'Build hypercube by moving object in Y direction:' is shown. 'Y-length, mm' is 100, 'frame/Y-res' is 276, 276. Radio buttons are set to 'Reflectance'. The 'Select file and Start' button is visible.

2 bands can be identified
by their wavelenghtes

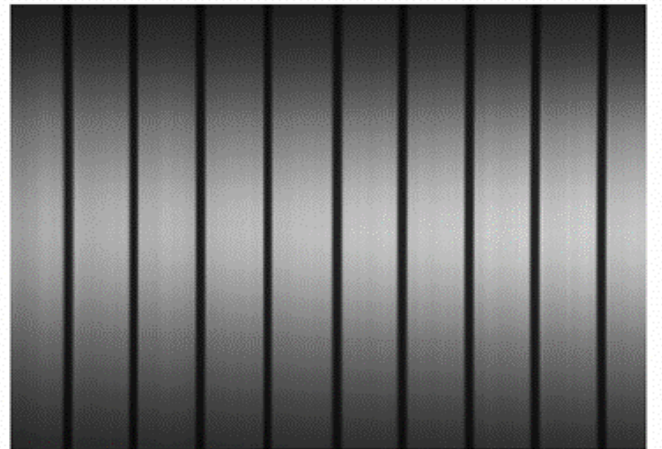
of sharpness of image



First the image was sharpened by using printed black lines and focusing the optics. Spatial alignment was checked.



Out of focus.



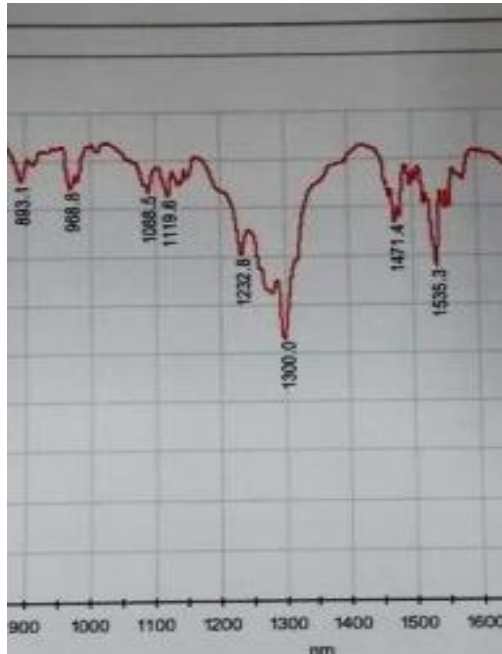
Focus OK.



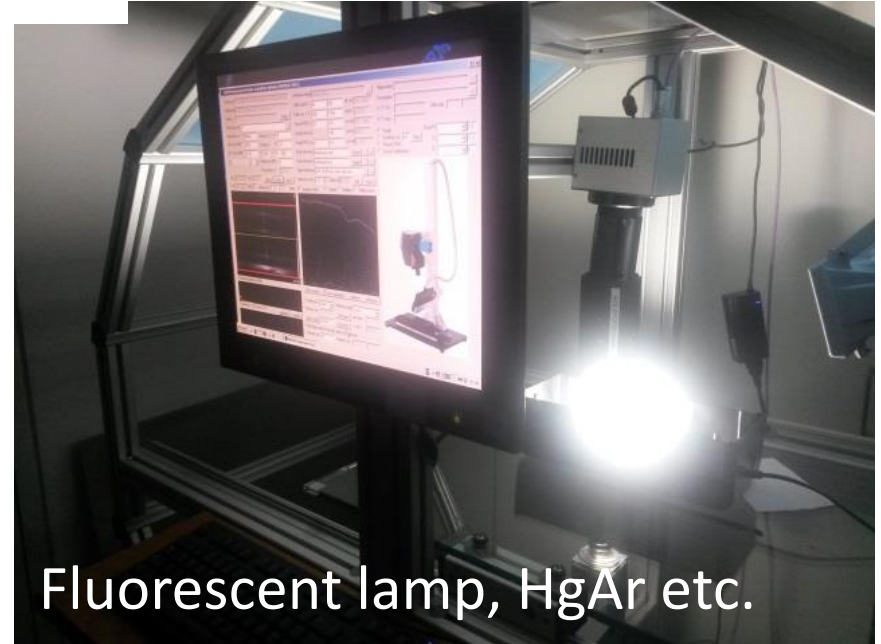
Spectral focusing

Zenith Polymer® Diffuse Reflectance Standards

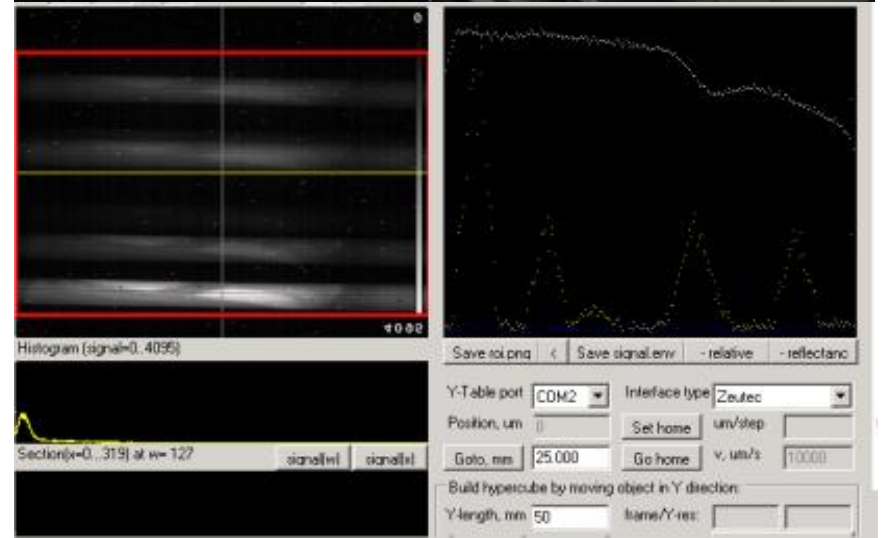
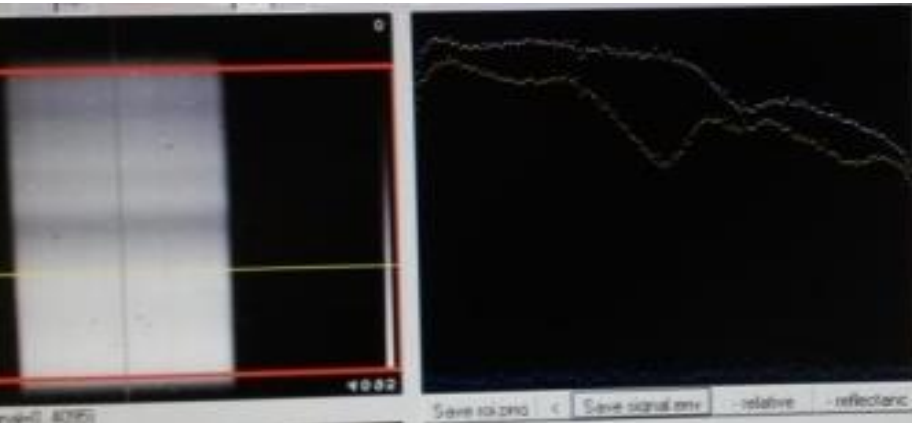
Department of Material Sciences
and Process Engineering



Sphereoptics



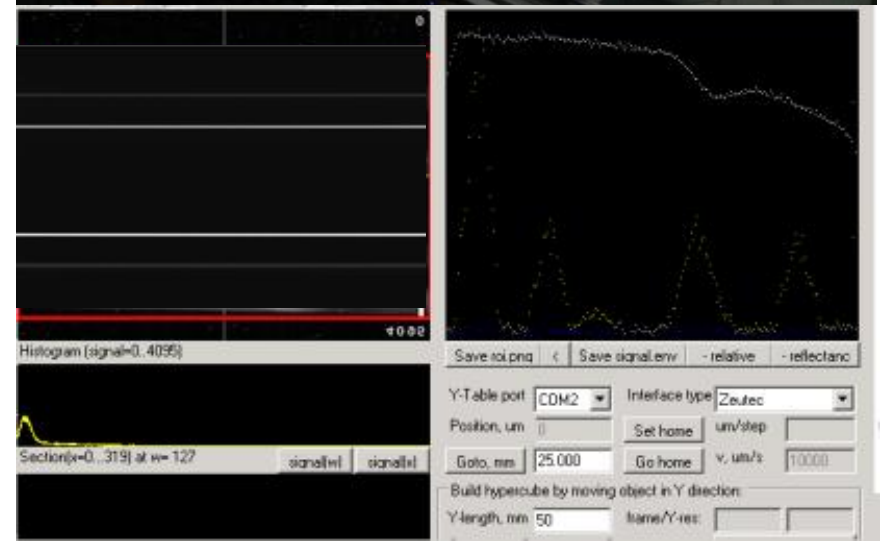
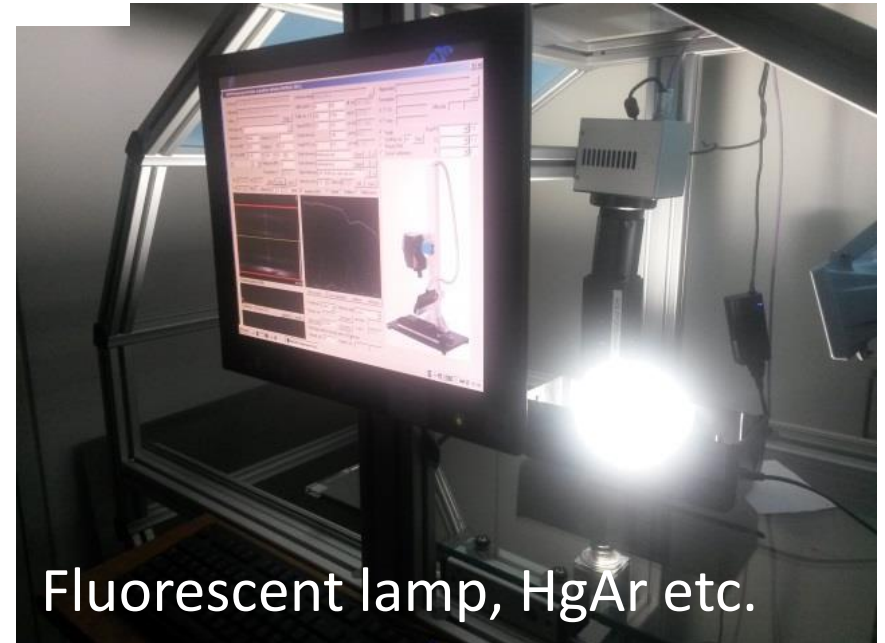
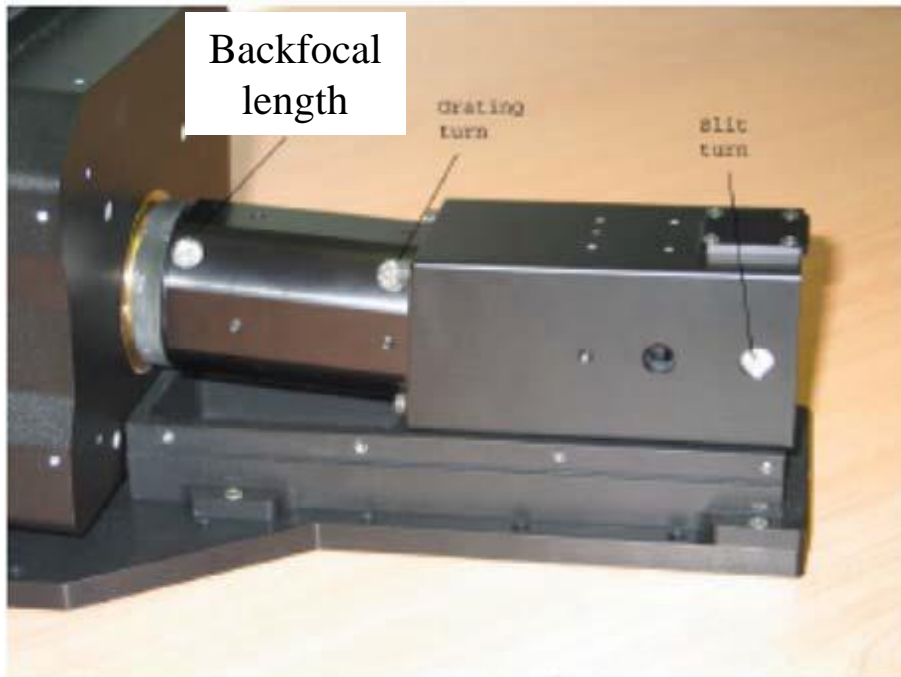
Fluorescent lamp, HgAr etc.



Spectral focusing

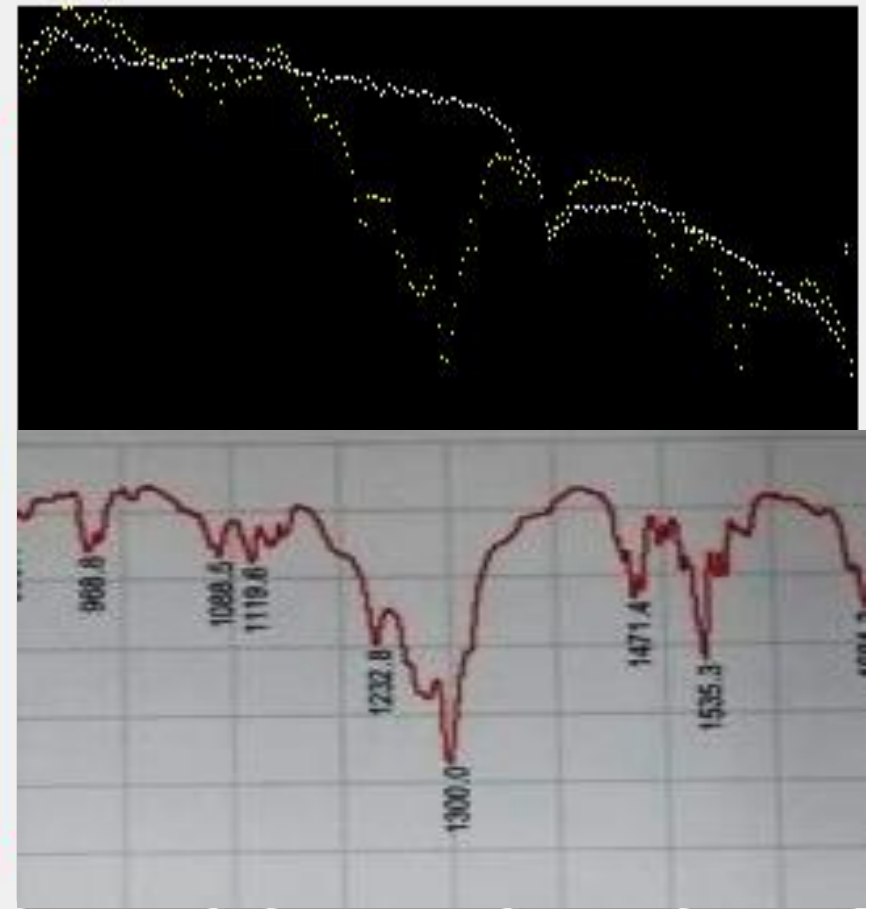
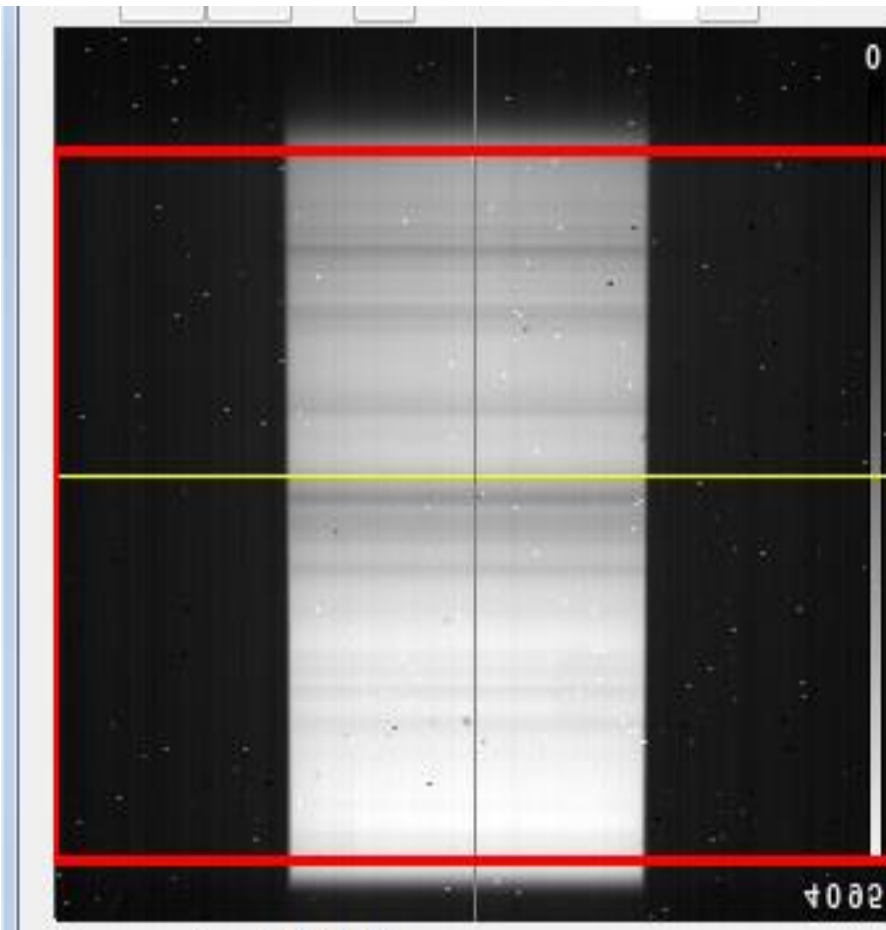
Zenith Polymer® Diffuse Reflectance Standards

- Spectral focusing was accomplished by adjusting the backfocal length
- Horizontal adjustment was done by moving the impspector respective to the camera



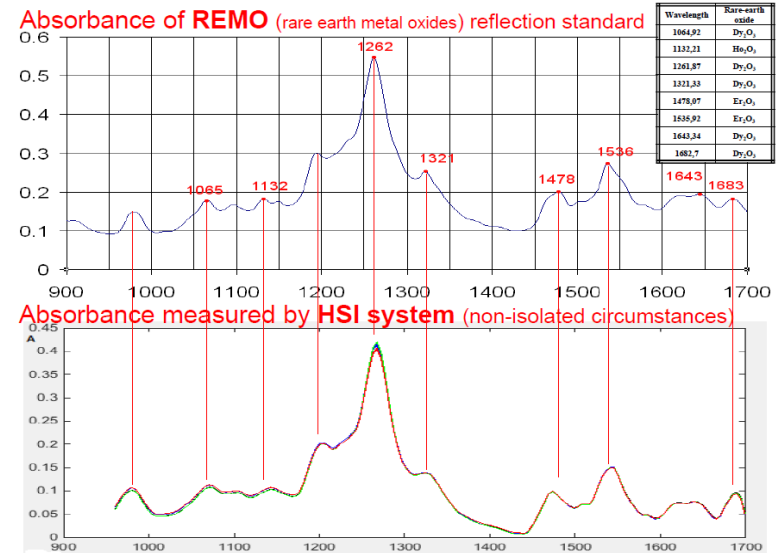
Spectral focusing

- Spectral features of Rare Earth element standard became visible, and spectral calibration could be performed.



Spectral calibration

- Alignment of matrix detector bands to known spectral bands
- Done in Argus software
 - Export of hyperspectral data of REE standard
 - Import in Excel
 - Looking for absorbance peaks (minimum reflection values at given matrix detector band)
 - Assignment of known spectral bands (nm) to detector bands (done in Argus)
 - Lower and upper end of spectrum – two-point calibration

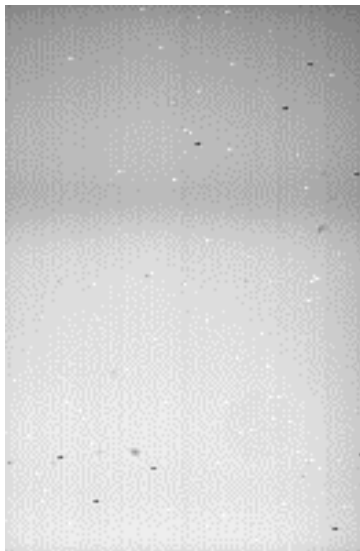


Software setting XevaNIR_hiper.ini

Calib: band1-2	59	175	all, nm	698 - 1924
Calib: nm 1-2	980	1536	nm/b	4,793103
Spectral ROI, b	55	210	roi, nm	961 - 1703
Spatial view, mm		116	um/px	362,5
Spatial ROI, px	0	319	roi, mm	0 - 115
Bright reference	whiteimage.png		Save	.. <
Dark reference	darkimage.png		Save	.. <

White and black reference

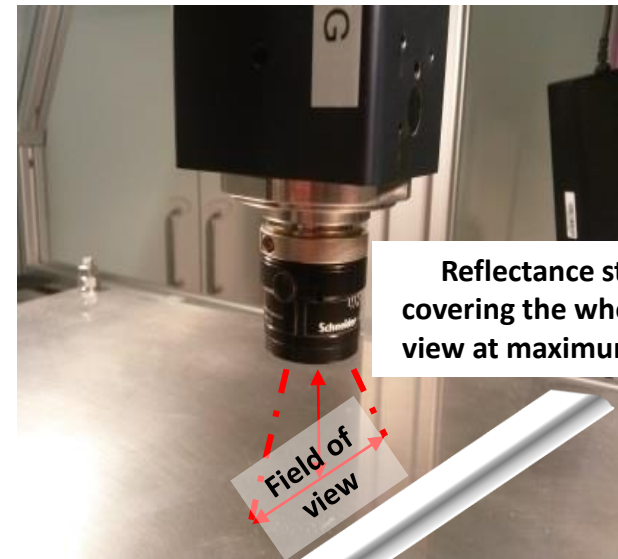
- White image is captured by using a Zenith polymer standard with 99 % reflection. The black image is captured by covering the lens of the optics by hand. Both images are saved by the Argus software as reference.



Software setting	XevaNIR_hiper.ini			..
Calib: band1-2	59	175	all, nm	698 - 1924
Calib: nm 1-2	980	1536	nm/b	4,793103
Spectral ROI, b	55	210	roi, nm	961 - 1703
Spatial view,mm		116	um/px	362,5
Spatial ROI, px	0	319	roi, mm	0 - 115
Bright reference	whiteimage.png	Save	..	<
Dark reference	darkimage.png	Save	..	<

Achievable spatial resolution

- Spatial resolution is a function of working distance
- It is determined by the field of view
- The field of view divided by the number of pixels (320) yields the spatial resolution



Software setting	_hiper.ini		
Calib: band1-2	59	175	all, nm 698 - 1924
Calib: nm 1-2	980	1536	nm/b 4,793103
Spectral ROI, b	55	210	roi, nm 961 - 1703
Spatial view, mm	116	um/px	362,5
Spatial ROI, px	0	319	roi, mm 0 - 115
Bright reference	whiteimage.png	Save	.. <
Dark reference	darkimage.png	Save	.. <

XCamera: XEVA-USB-FPA-320-100Hz (BUSY,IP=,PID=8110,SER=)

drv: Xeneth typ: NIR X-B-bit: 320 256 12

Calibration: XEVA6179_80ms_LG_RT_new_6179.xca

Setting:

Video logic, ttb:

Integration, us: 80000 LowGain level 0-3

ADC Vin, 4095: 2730 Cooling settle, C: 164,85

ADC Vref, 4095: 2123 P: 3000 I: 150 D: 1

Peltier: 0 temp, C: -11,32

Noise th%/n: 50 1 show

Intvl/Dur, ms: 200 34 fra 0 / jump, tck drop: 24 66 94

Software setting: Zeutec_NIR.ini

Calib: band 1-2: 45 200 all, nm: 668 - 1989

Calib: nm 1-2: 900 1700 nm/b: 5,16129

Spectral ROI, b: 18 220 roi, nm: 761 - 1803

Spatial view, mm: 135 um/px: 421,875

Spatial ROI, px: 0 319 roi, mm: 0 - 134

Bright frame: whiteimage.png

Dark frame: darkimage.png

AbsRef of bright: SRT-99-050 abs reflectance.txt

Section x=160 Signal Reflectance Absolute

Hypercube: 0305_12_fourth Argus version_200 invl_2_log21

Description: Argos output: relative [03.05.2015 11:55:02]

X*Y*B: 319 * 190 * 202 Min,max: 0 1

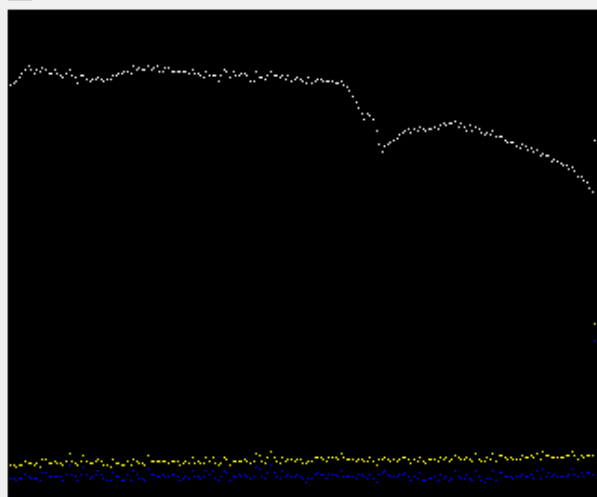
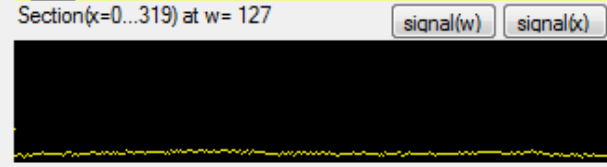
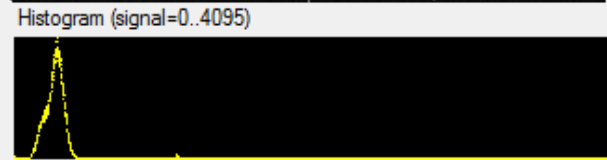
X*Y size: 134,618mm * 80,180

Single Gray/R: 760.65 1.0

Scroll by, ms: 50

Pseudo RGB G: 1276.77 -1.0

Linear Combination B: 1798.06 0



Y-Table port: COM1 Interface type: Zeutec

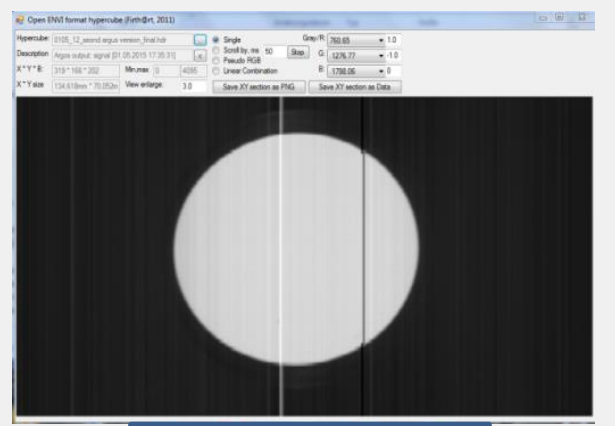
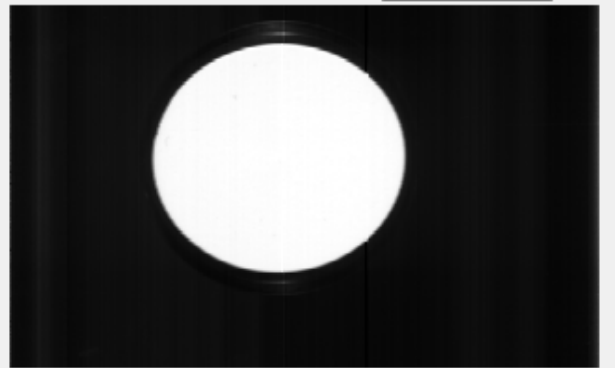
Position, um: 79250 um/step:

25.000 v, um/s: 10000

Build hypercube by moving object in Y direction:

Y-length, mm: 80 frame/Y-res: 190 190

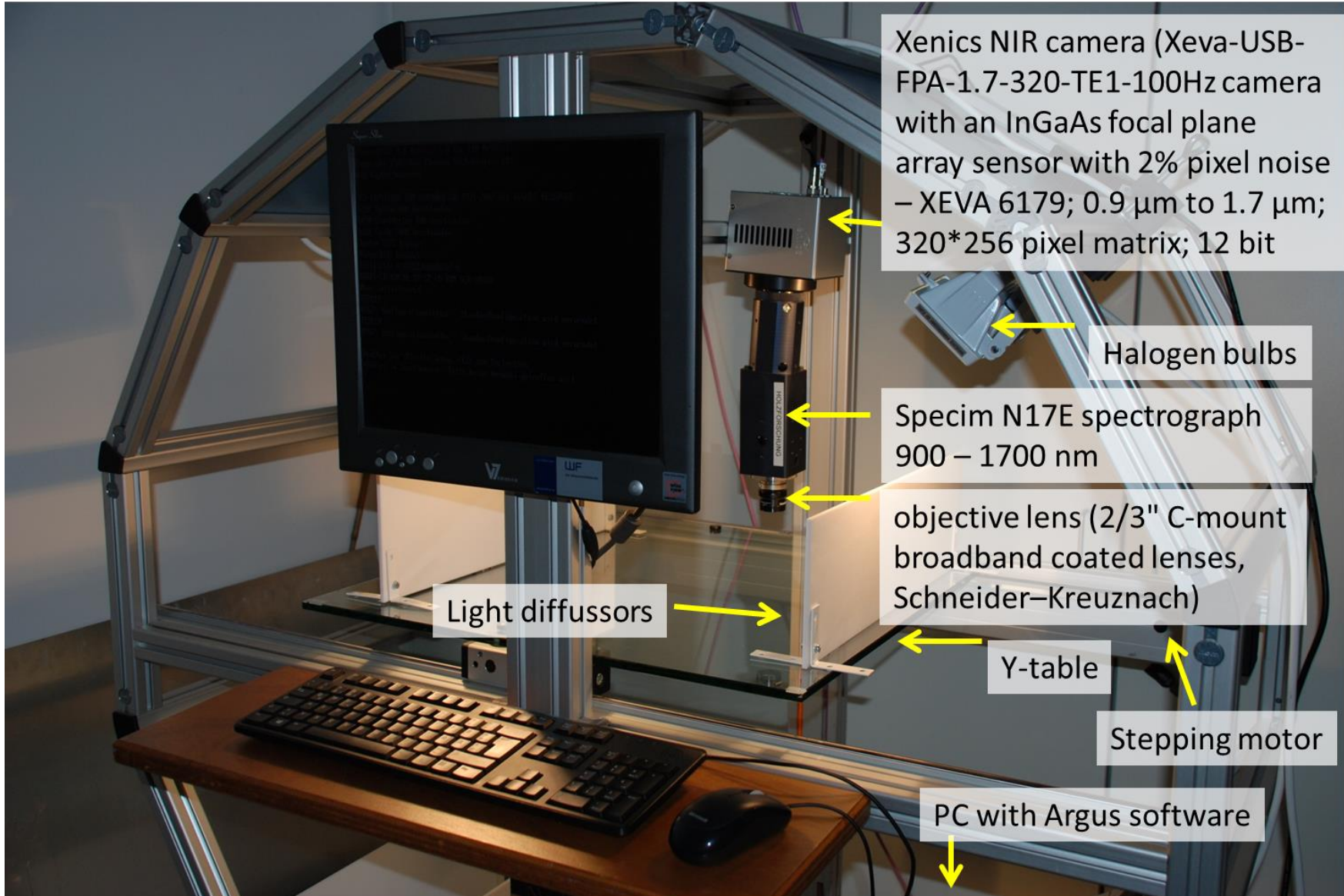
Signal Reflectance Absolute



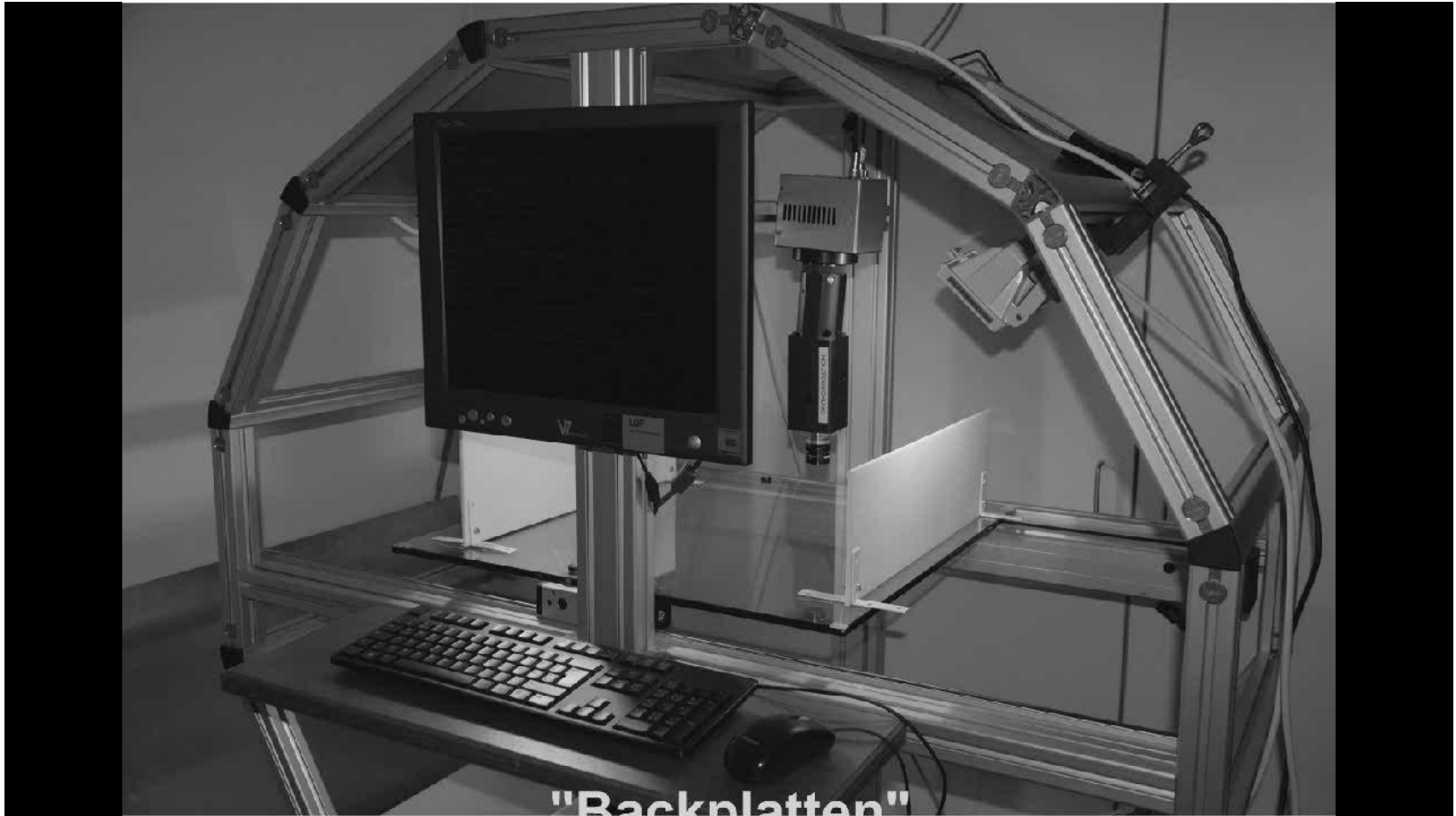
Bad pixels

Enlarge window to see bigger, than x=320px * y=500px image =>

Working HSI system on BOKU



See how it works...



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² Physics-Control Department, Faculty of Food Science, Corvinus University of Budapest, Budapest Somlói út 14-16, H-1113, Hungary
³ Trees and Timber Institute/National Research Council, IVALSA/INR, Via Biasi 75, San Michele All'Adige, Italy

Motivation

- Determination of wood quality for an efficient utilization of harvested logs.
- Detection of wood deficiencies in an early stage of the production chain.
- Using Hyperspectral imaging to assess wood quality parameters in the field.

Hyperspectral Imaging

by HeadWall Photonics push-broom hyperspectral system (Fig. 1 - Xenics NIR camera: 320° 256 matrix, 14 bit A/D, 5 nm resolution, 250 mm Y-table gear, stable diffuse 45/0 illumination).

Results highlighting the possibilities of the application of this technique even on freshly cut logs (Fig. 2a):

- areas affected by fungi could be clearly identified, even in an early stage of attack - not visible to naked eye (Fig. 2c)
- areas with structural abnormalities could be clearly identified
- dry and humid wood could be measured
- measurements could be performed on a rough surface

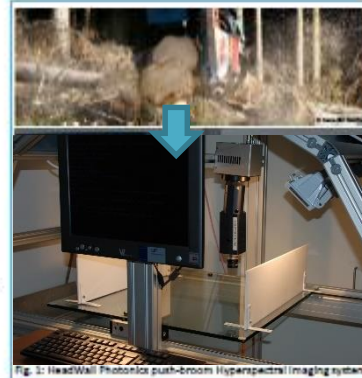


Fig. 1: HeadWall Photonics push-broom Hyperspectral imaging system.

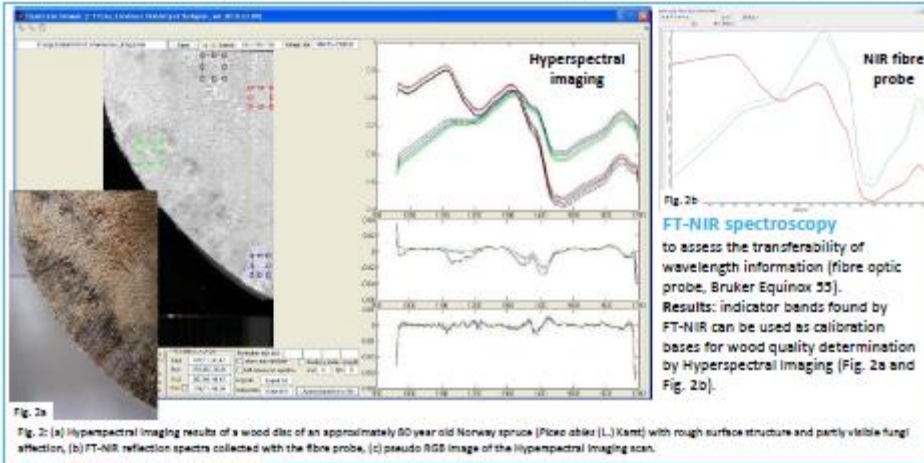


Fig. 2a

Fig. 2: (a) Hyperspectral imaging results of a wood disc of an approximately 80-year old Norway spruce (Picea abies (L.) Kant) with rough surface structure and partly visible fungi affection, (b) FT-NIR reflection spectra collected with the fibre probe, (c) pseudo RGB image of the hyperspectral imaging scan.

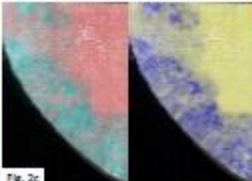


Fig. 2c

Result: a gradient not visible to the naked eye could be visualized by

Outlook

Hyperspectral Imaging is a promising technique to improve fast on-site judgment of log quality. Issues due to influences of

- uneven distribution of wetness in the log,
- rough surfaces on the measurements,
- cracks and other inhomogeneities on the measurements,
- contaminations with soil or machine oil etc.

have to answered in further research within the SLOPE-project.

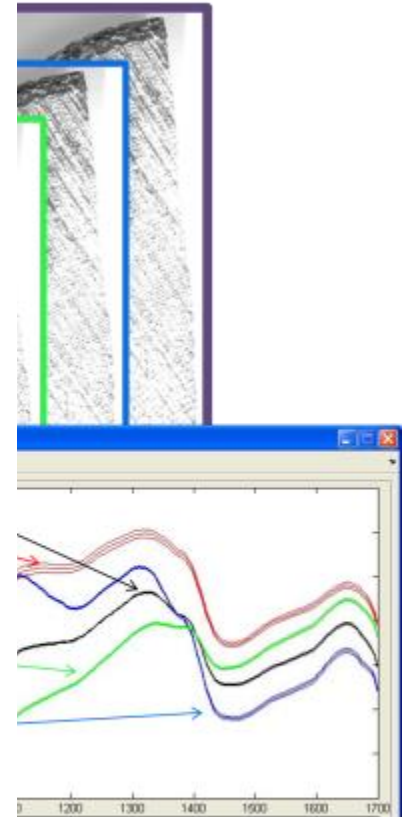
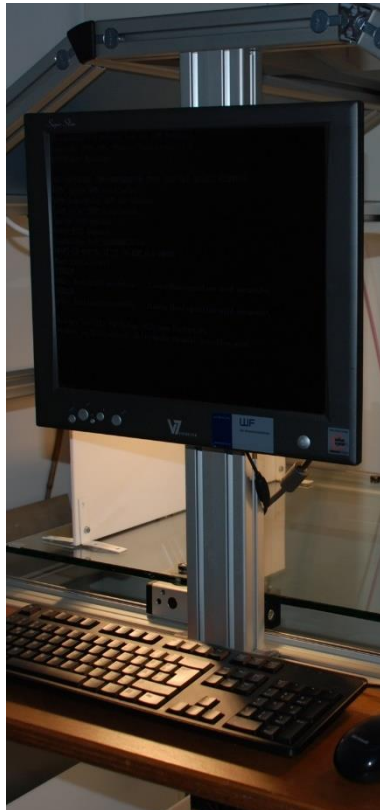
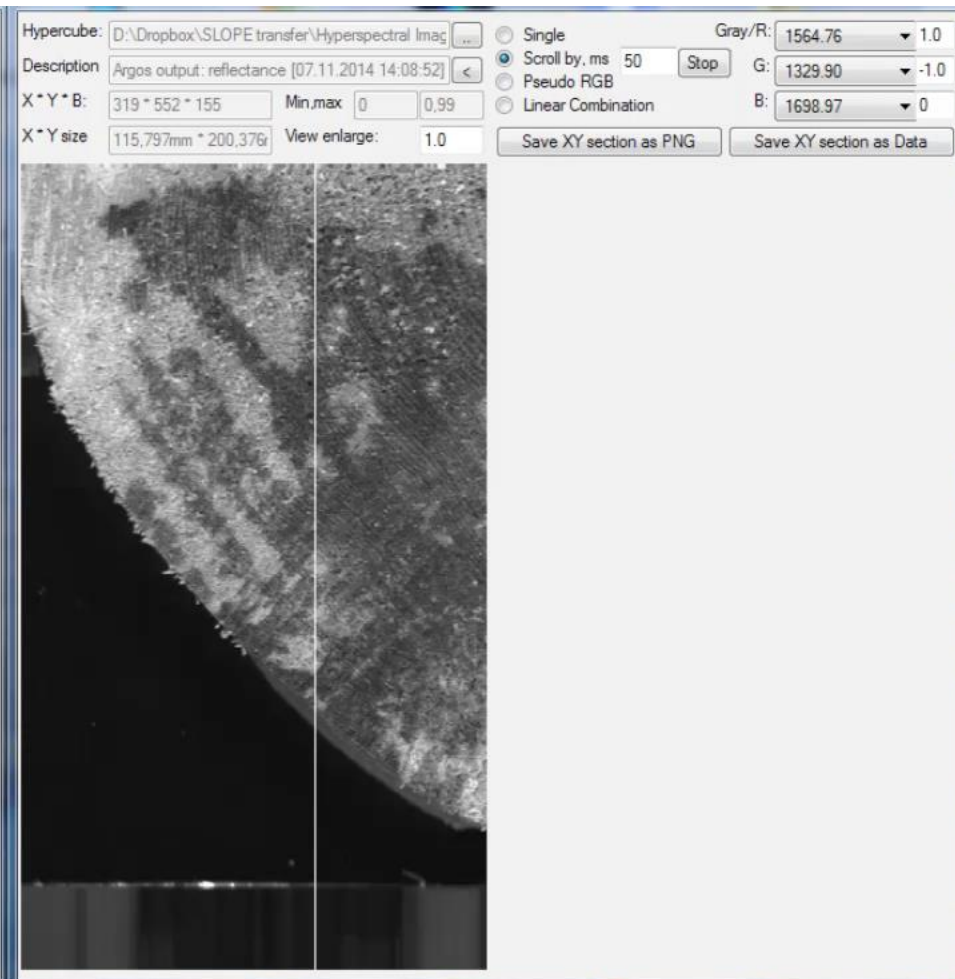
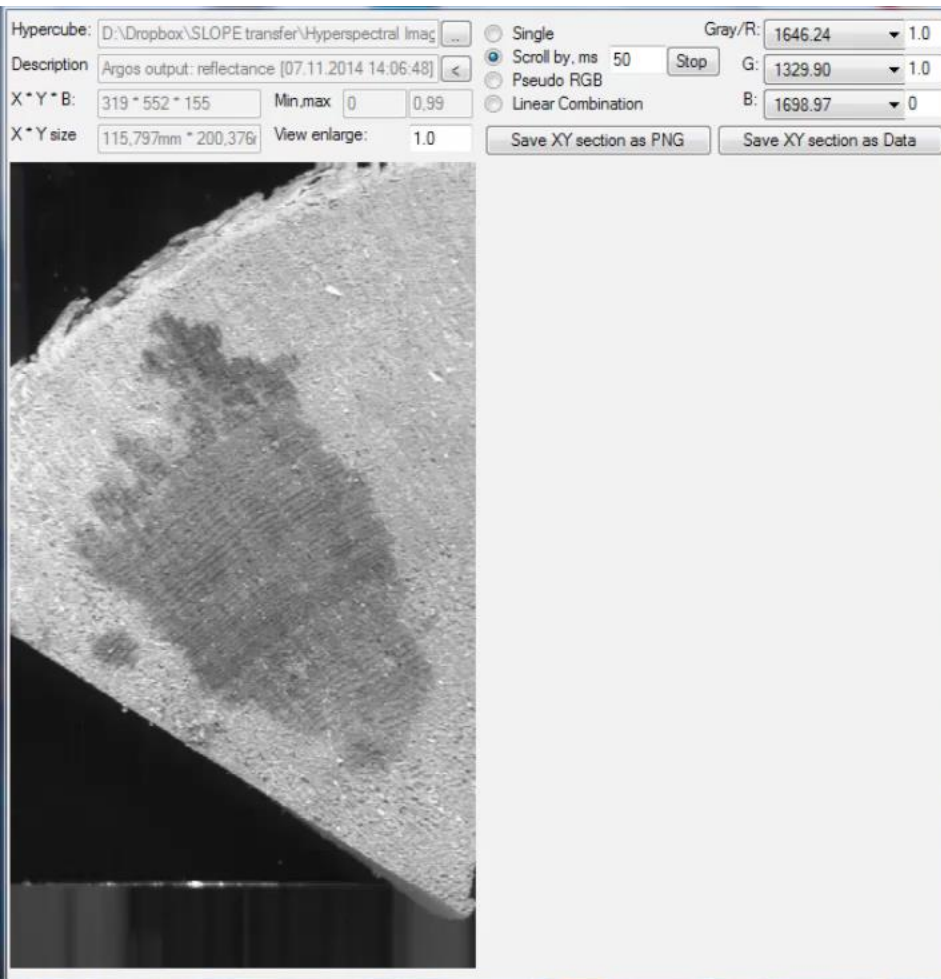


Fig. 2b
FT-NIR spectroscopy
 to assess the transferability of wavelength information (fibre optic probe, Bruker Equinox 55). Results: indicator bands found by FT-NIR can be used as calibration bases for wood quality determination by Hyperspectral imaging (Fig. 2a and Fig. 2b).

First res
wood,



Water band and fungus



SLOPE project - Hyperspectral imaging (HI) for the determination of log/biomass "HI quality index"



25 samples of spruce (*Picea abies*) with different defects (\varnothing 15 - 45 cm), March 2015

BOKU education forest at Forchtenstein (Rosalia), Burgenland



SLOPE project - Hyperspectral imaging (HI) for the determination of log/biomass “HI quality index”



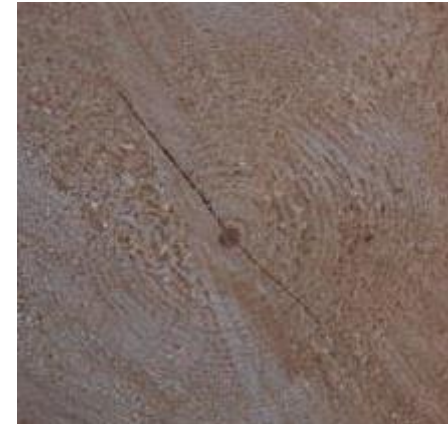
resin pockets



knots



shakes, checks, splits



eccentric pith + compression wood + rot

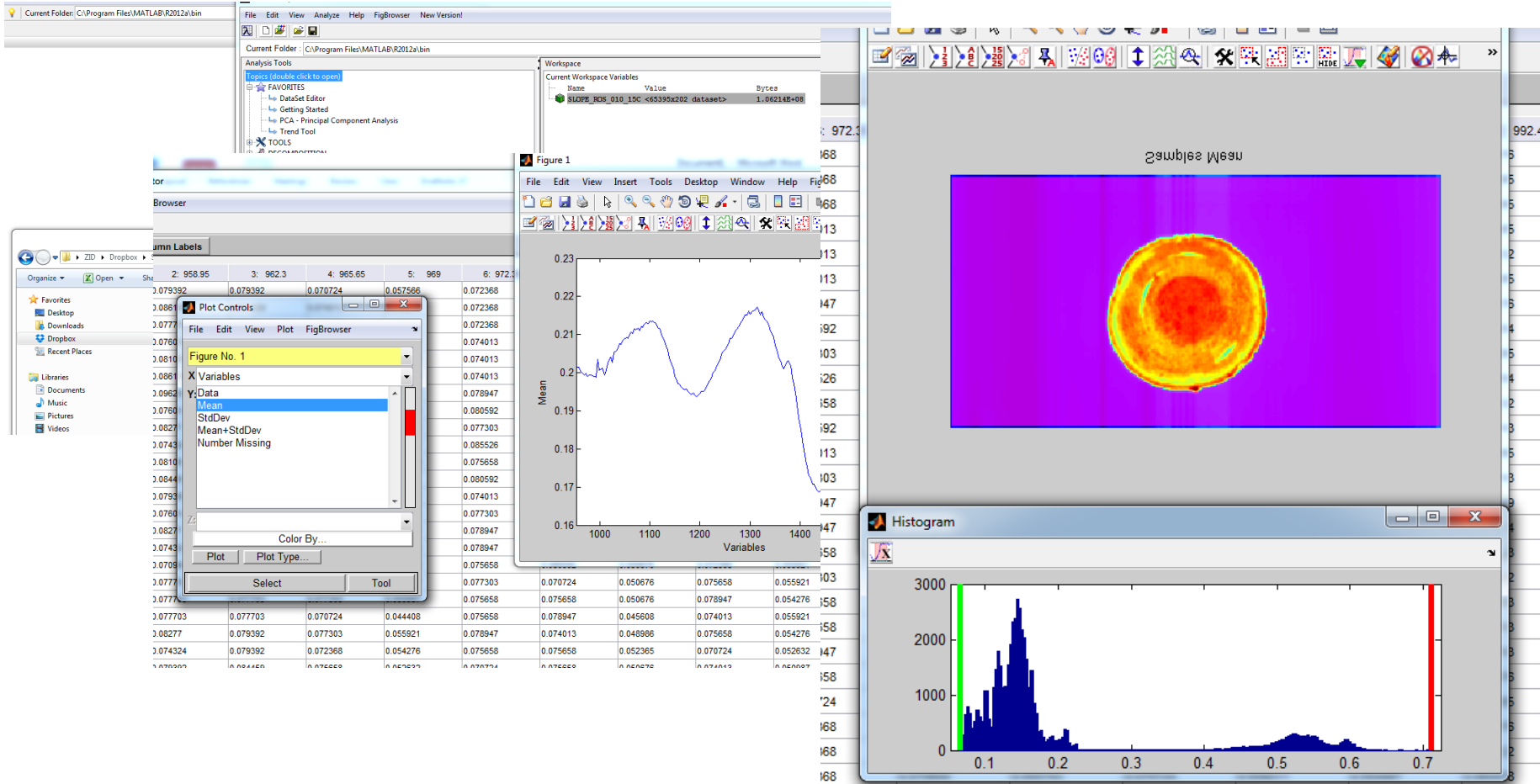


**Measured with FT-NIR
and hyperspectral imaging at
BOKU, and MicroNIR and
Hamamatsu at CNR**

eccentric pith + rot + knot



SLOPE: data analysis with PLS toolbox (Eigenvector software)



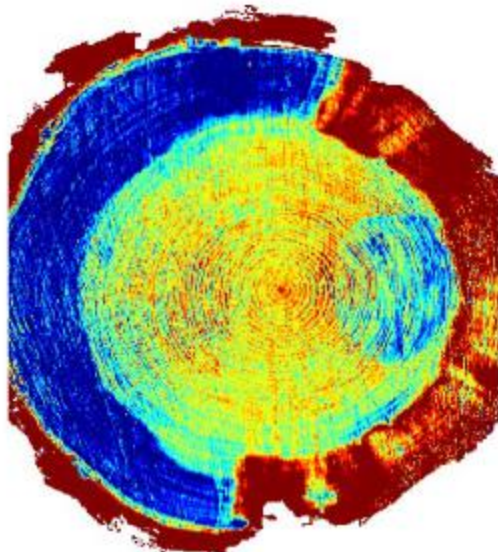
Images of

In our case: 1.4 x 1.4 mm

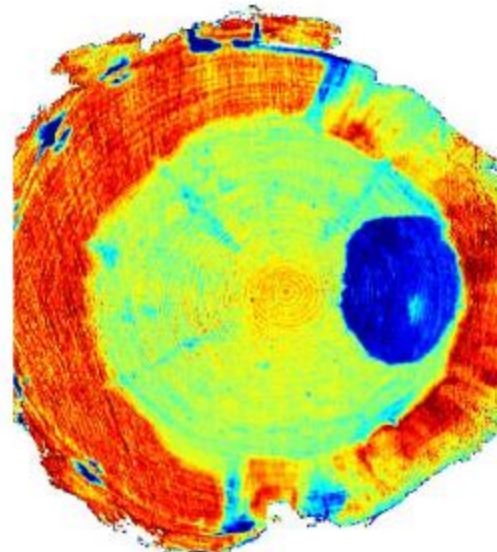
(450 mm spatial view / 320 Pixels = 1.406 mm)



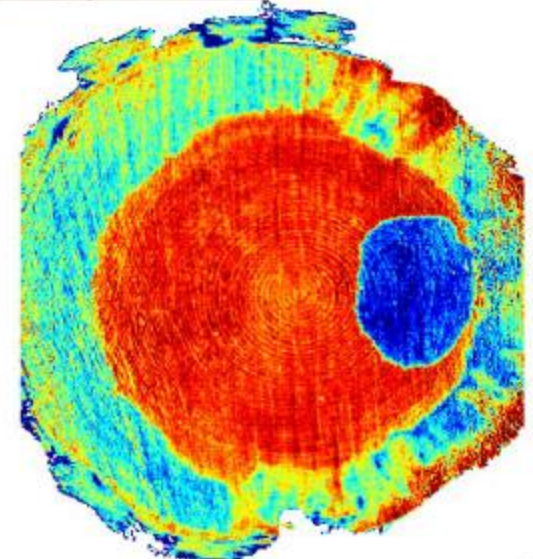
high
value
low
value



PC 1



PC 2

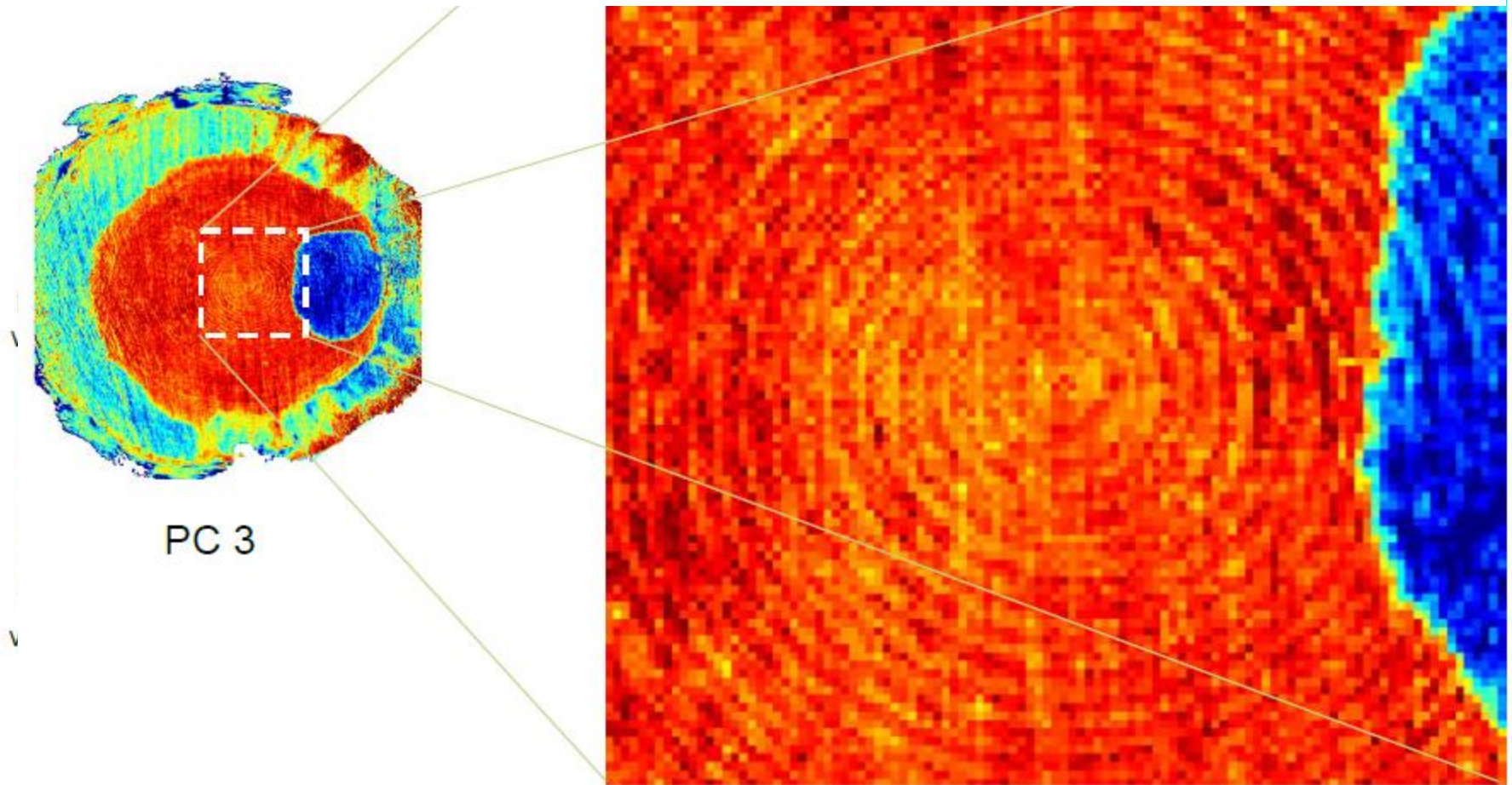


PC 3

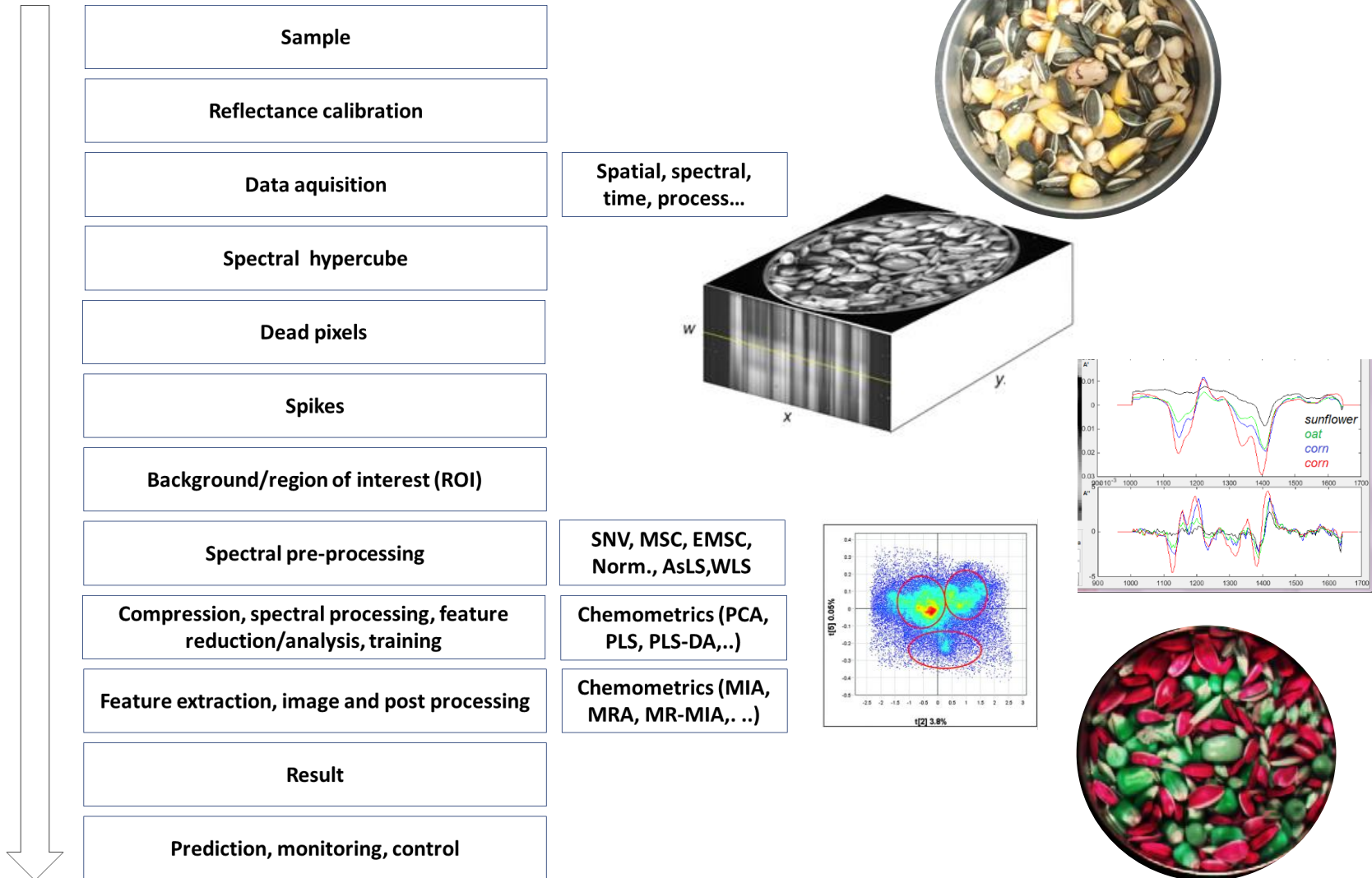
Spatial resolution / pixel size: 1 mm x 1 mm

In our case: 1.4 x 1.4 mm

(450 mm spatial view / 320 Pixels = 1.406 mm)



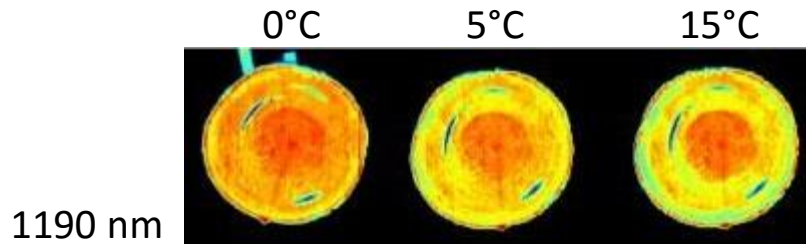
Ability to apply workflow of HSI



SLOPE project – analytical challenges

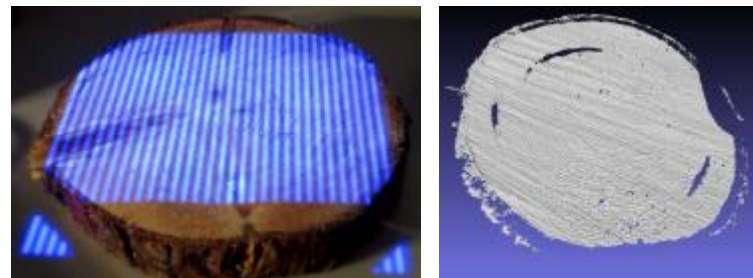


- Temperature



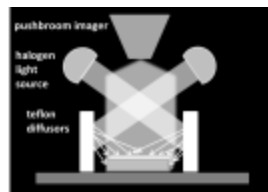
Measurements at different temperatures yield temperature effect

- Roughness



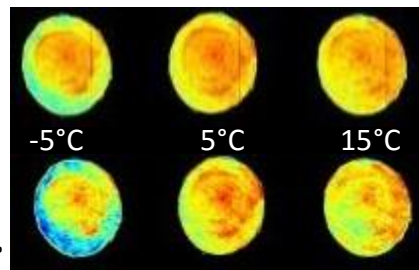
Roughness can be calculated by z-values of 3D scan

- Lightning & referencing



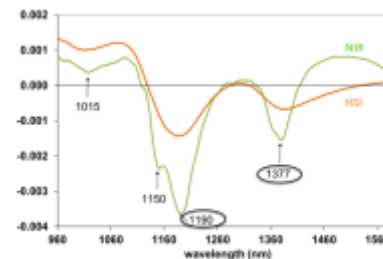
Diffuse lightning reduces morphological effects, needs to be carefully considered

- Water & Ice



1190 nm

1377 nm



Ice and water have specific bands, wavelength selection important

- Other contam.

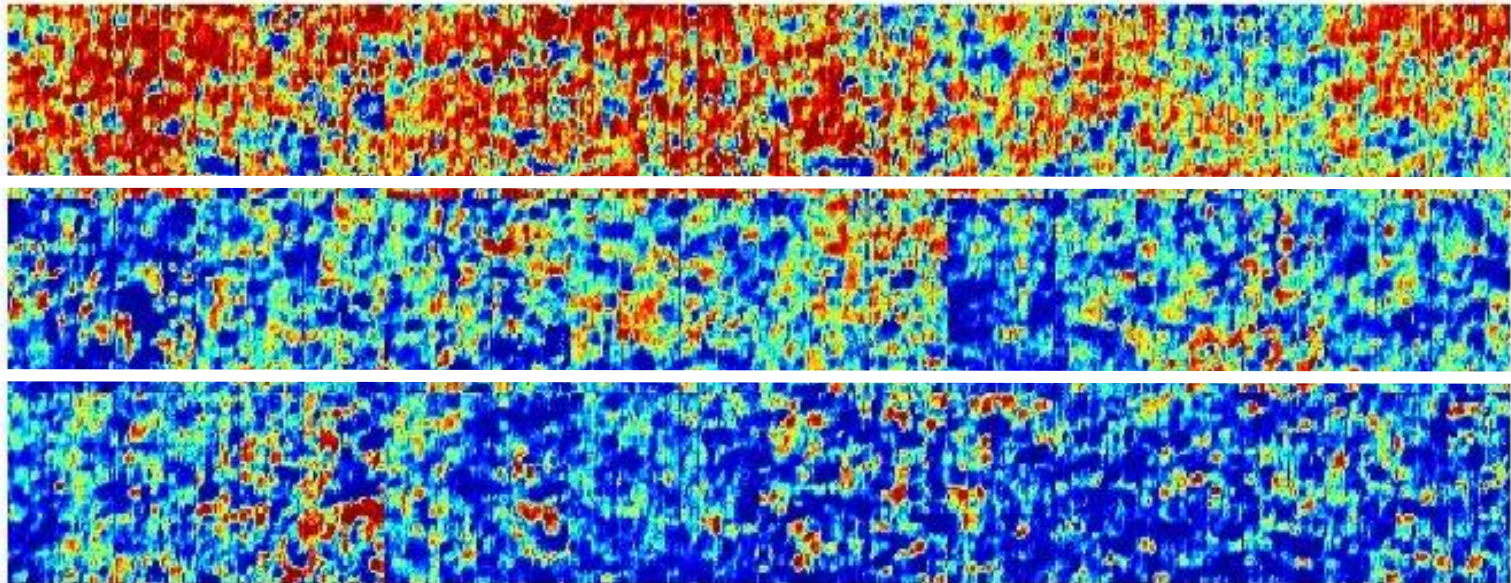
HSI of mycotoxins secondary metabolites of *Fusarium* in maize



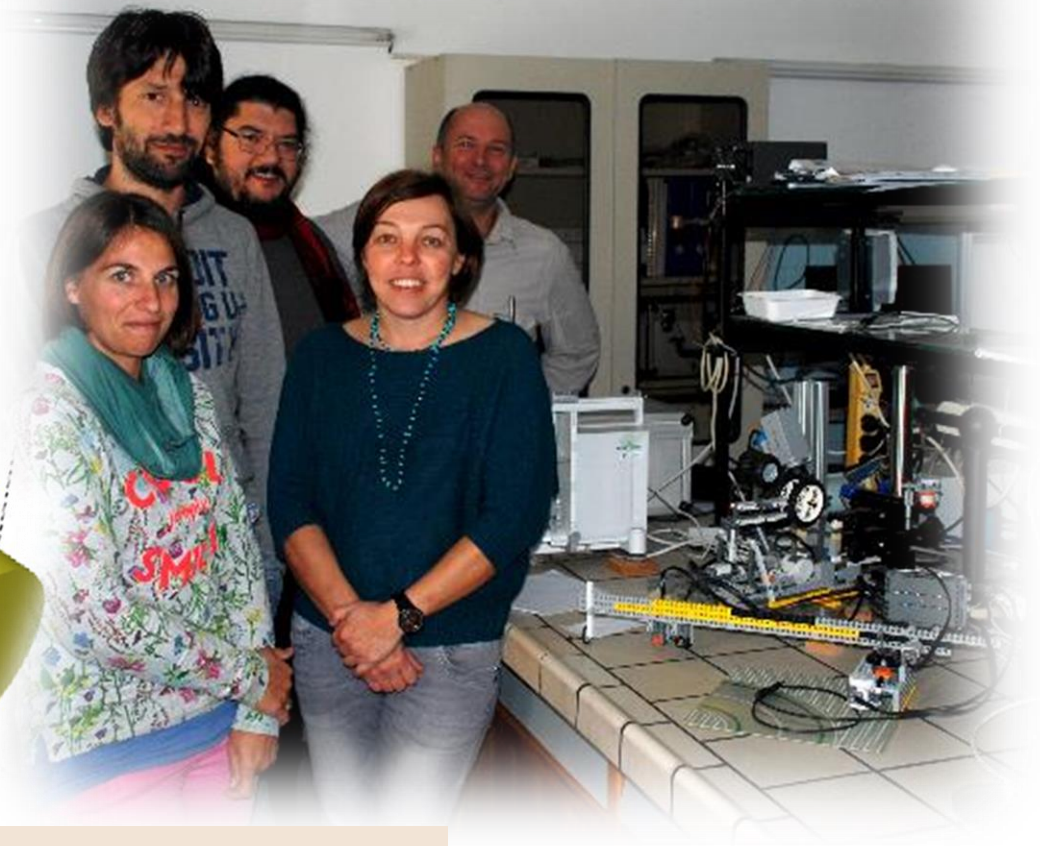
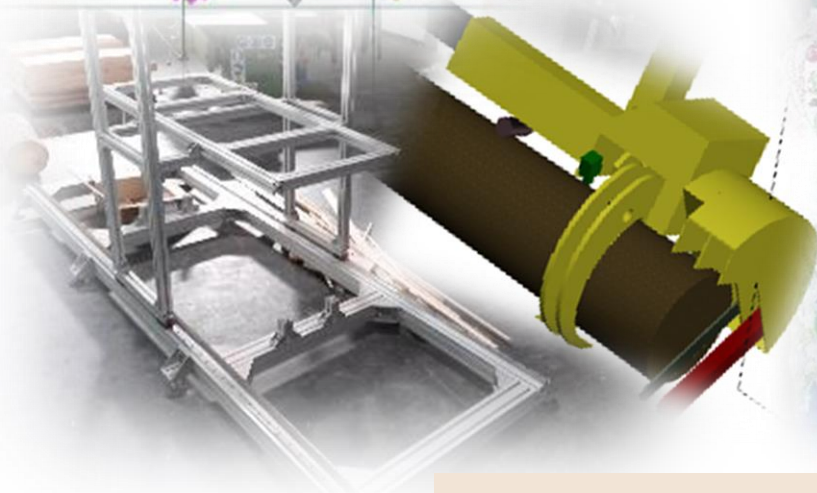
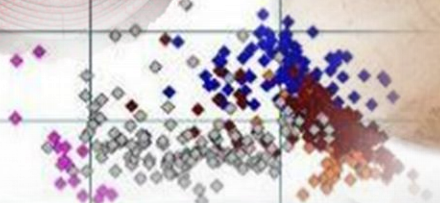
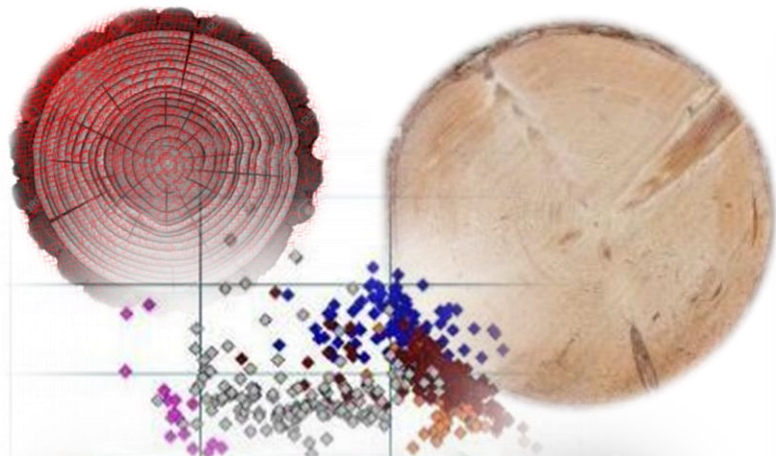
Parrag, Sulyok, Firtha, Felföldi, Zitek, Krska, Hinterstoisser (in prepr): Application of HSI to detect toxigenic *Fusarium* infection in maize.

HSI of mycotoxins secondary metabolites of *Fusarium* in maize

Image of Class Pred Probability G



Parrag, Sulyok, Firtha, Felföldi, Zitek, Krska, Hinterstoisser (in prepr): Application of HSI to detect toxigenic *Fusarium* infection in maize.



Thank you for your interest!

andreas.zitek@boku.ac.at

<https://viris.boku.ac.at/wshyperspectral2015/wshyperspectral2015/PROGRAMME.html>



SLOPE and BiRT WORKSHOP
HYPERSPECTRAL IMAGING
RENEWABLE RESOURCES, BIOMATERIALS AND FOOD
UFT TULLN - 2015-03-20

